

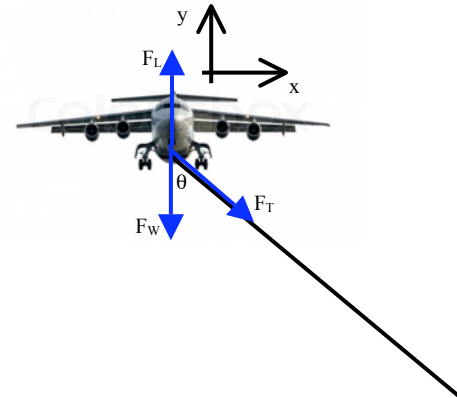
Name \_\_\_\_\_

Physics 110 Quiz #3, October 11, 2013

Please show all work, thoughts and/or reasoning in order to receive partial credit. The quiz is worth 10 points total.

I affirm that I have carried out my academic endeavors with full academic honesty.

A remote controlled airplane has a mass of  $1.5\text{kg}$ . It is attached to a  $2.0\text{m}$  long string (you're holding the other end) and the plane is flown in a horizontal circle at a constant speed. The string makes a  $20^\circ$  angle with respect to the vertical and the plane takes  $1.5\text{s}$  to complete one circular orbit. The airflow over the wings of the plane generates a lifting force  $F_L$  that is always perpendicular to the wings of the plane.



1. What is the lifting force  $F_L$  generated by the wings?

$$\sum F_x : F_T \sin \theta = ma_x = m \frac{v^2}{r} = m \left( \frac{2\pi r}{T} \right)^2 = \frac{4\pi^2 r m}{T^2} = \frac{4\pi^2 (L \sin \theta) m}{T^2} \rightarrow F_T = \frac{4\pi^2 L m}{T^2}$$
$$\sum F_y : F_L - F_W - F_T \cos \theta = ma_y = 0 \rightarrow F_L = F_W + F_T \cos \theta = \left( 1.5\text{kg} \times 9.8 \frac{\text{m}}{\text{s}^2} \right) + 52.6\text{N} = 64.2\text{N}$$

directed vertically upwards from the wings.

2. What is the tension force  $F_T$  in the string?

$$F_T = \frac{4\pi^2 m L}{T^2} = \frac{4\pi^2 (1.5\text{kg})(2\text{m})}{(1.5\text{s})^2} = 52.6\text{N}$$

directed along the string away from the plane.

3. Suppose that the angle that the string makes with the vertical is constant and that the plane is able to fly at a speed that is greater than that of the initial problem. In this case

- a.  $F_L \uparrow$  and  $F_T \uparrow$ .
- b.  $F_L \downarrow$  and  $F_T \uparrow$ .
- c.  $F_L \uparrow$  and  $F_T \downarrow$ .
- d.  $F_L \downarrow$  and  $F_T \downarrow$ .

**Useful formulas:**

**Motion in the r = x, y or z-directions**

$$r_f = r_0 + v_{0r}t + \frac{1}{2}a_r t^2$$

$$v_{fr} = v_{0r} + a_r t$$

$$v_{fr}^2 = v_{0r}^2 + 2a_r \Delta r$$

**Uniform Circular Motion**

$$a_r = \frac{v^2}{r}$$

$$F_r = ma_r = m \frac{v^2}{r}$$

$$v = \frac{2\pi r}{T}$$

$$F_G = G \frac{m_1 m_2}{r^2}$$

**Geometry /Algebra**

Circles    Triangles    Spheres

$$C = 2\pi r \quad A = \frac{1}{2}bh \quad A = 4\pi r^2$$

$$A = \pi r^2 \quad V = \frac{4}{3}\pi r^3$$

Quadratic equation :  $ax^2 + bx + c = 0$ ,

whose solutions are given by :  $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$

**Vectors**

magnitude of a vector =  $\sqrt{v_x^2 + v_y^2}$

direction of a vector  $\rightarrow \phi = \tan^{-1}\left(\frac{v_y}{v_x}\right)$

**Useful Constants**

$$g = 9.8 \text{ m/s}^2 \quad G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2$$

$$N_A = 6.02 \times 10^{23} \text{ atoms/mole} \quad k_B = 1.38 \times 10^{-23} \text{ J/K}$$

$$\sigma = 5.67 \times 10^{-8} \text{ W/m}^2\text{K}^4 \quad v_{\text{sound}} = 343 \text{ m/s}$$

**Linear Momentum/Forces**

$$\vec{p} = m \vec{v}$$

$$\vec{p}_f = \vec{p}_i + \vec{F} \Delta t$$

$$\vec{F} = m \vec{a}$$

$$\vec{F}_s = -k \vec{x}$$

$$F_f = \mu F_N$$

**Work/Energy**

$$K_t = \frac{1}{2}mv^2$$

$$K_r = \frac{1}{2}I\omega^2$$

$$U_g = mgh$$

$$U_s = \frac{1}{2}kx^2$$

$$W_T = Fd \cos \theta = \Delta E_T$$

$$W_R = \tau \theta = \Delta E_R$$

$$W_{\text{net}} = W_R + W_T = \Delta E_R + \Delta E_T$$

$$\Delta E_R + \Delta E_T + \Delta U_g + \Delta U_s = 0$$

$$\Delta E_R + \Delta E_T + \Delta U_g + \Delta U_s = -\Delta E_{\text{diss}}$$

**Heat**

$$T_C = \frac{5}{9}[T_F - 32]$$

$$T_F = \frac{9}{5}T_C + 32$$

$$L_{\text{new}} = L_{\text{old}}(1 + \alpha \Delta T)$$

$$A_{\text{new}} = A_{\text{old}}(1 + 2\alpha \Delta T)$$

$$V_{\text{new}} = V_{\text{old}}(1 + \beta \Delta T) : \beta = 3\alpha$$

$$PV = Nk_B T$$

$$\frac{3}{2}k_B T = \frac{1}{2}mv^2$$

$$\Delta Q = mc \Delta T$$

$$P_C = \frac{\Delta Q}{\Delta t} = \frac{kA}{L} \Delta T$$

$$P_R = \frac{\Delta Q}{\Delta T} = \epsilon \sigma A \Delta T^4$$

$$\Delta U = \Delta Q - \Delta W$$

**Rotational Motion**

$$\theta_f = \theta_i + \omega_i t + \frac{1}{2}\alpha t^2$$

$$\omega_f = \omega_i + \alpha t$$

$$\omega_f^2 = \omega_i^2 + 2\alpha \Delta \theta$$

$$\tau = I\alpha = rF$$

$$L = I\omega$$

$$L_f = L_i + \tau \Delta t$$

$$\Delta s = r \Delta \theta : v = r\omega : a_t = r\alpha$$

$$a_r = r\omega^2$$

**Fluids**

$$\rho = \frac{M}{V}$$

$$P = \frac{F}{A}$$

$$P_d = P_0 + \rho g d$$

$$F_B = \rho g V$$

$$A_1 v_1 = A_2 v_2$$

$$\rho_1 A_1 v_1 = \rho_2 A_2 v_2$$

$$P_1 + \frac{1}{2}\rho v_1^2 + \rho g h_1 = P_2 + \frac{1}{2}\rho v_2^2 + \rho g h_2$$

**Simple Harmonic Motion/Waves**

$$\omega = \sqrt{\frac{k}{m}} = 2\pi f = \frac{2\pi}{T}$$

$$T_s = 2\pi \sqrt{\frac{m}{k}}$$

$$T_p = 2\pi \sqrt{\frac{l}{g}}$$

$$v = \pm \sqrt{\frac{k}{m} A \left(1 - \frac{x^2}{A^2}\right)^{\frac{1}{2}}}$$

$$x(t) = x_{\text{max}} \sin(\omega t) \text{ or } x_{\text{max}} \cos(\omega t)$$

$$v(t) = v_{\text{max}} \cos(\omega t) \text{ or } -v_{\text{max}} \sin(\omega t)$$

$$a(t) = -a_{\text{max}} \sin(\omega t) \text{ or } -a_{\text{max}} \cos(\omega t)$$

$$v_{\text{max}} = \omega x_{\text{max}} : a_{\text{max}} = \omega^2 x_{\text{max}}$$

$$v = f\lambda = \sqrt{\frac{F_T}{\mu}}$$

$$f_n = n f_1 = n \frac{v}{2L}$$

$$I = 2\pi^2 f^2 \rho v A^2$$

**Sound**

$$v = f\lambda = (331 + 0.6T) \frac{\text{m}}{\text{s}}$$

$$\beta = 10 \log \frac{I}{I_0}; \quad I_0 = 1 \times 10^{-12} \frac{\text{W}}{\text{m}^2}$$

$$f_n = n f_1 = n \frac{v}{2L}; \quad f_n = n f_1 = n \frac{v}{4L}$$