Name

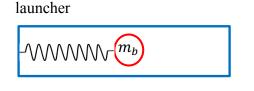
Physics 110 Quiz #5, May 8, 2020

*Please show all work, thoughts and/or reasoning in order to receive partial credit. The quiz is worth 10 points total.* 

I affirm that I have carried out my academic endeavors with full academic honesty.

A small steel ball of mass  $m_b = 50g$  is shot from a horizontal launcher in to a block of wood of mass M = 5kg, initially at rest.

a. To launch the ball from the launcher, the ball is compressed against a horizontal spring of stiffness k by an amount |x| = 10cm (measured from the equilibrium position of the spring.) If the ball is launched from rest and loses contact with the spring when the spring returns to its equilibrium length with a speed of  $v_b = 300\frac{m}{s}$ , what is the stiffness k of the spring?



Since the ball is fired horizontally  $\Delta U_g = 0$ . The initial stored elastic potential energy is transformed to kinetic energy.

$$\Delta E = \Delta K + \Delta U_g + \Delta U_s = 0$$
  

$$\Delta E = \left(\frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2\right) + \left(\frac{1}{2}kx_f^2 - \frac{1}{2}kx_i^2\right) = 0$$
  

$$k = \frac{mv_f^2}{x_i^2} = \frac{0.05kg(300\frac{m}{s})^2}{(0.1m)^2} = 4.5 \times 10^5 \frac{N}{m}$$

b. After launch, the ball strikes the stationary block and imbeds itself in the block. What is the speed of the ball & block after the bullet comes to rest in the block?



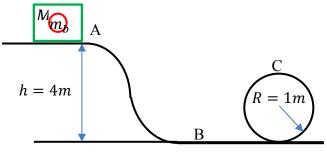
We have a collision and we apply conservation of momentum.

$$\Delta p_x = p_{fx} - p_{ix} = 0$$
  

$$p_{ix} = p_{fx} \to m_b v_b = (m_b + M)V$$
  

$$V = \frac{m_b}{m_b + M} v_b = \frac{0.05kg}{0.05kg + 5kg} \times 300\frac{m}{s} = 2.97\frac{m}{s}$$

c. Suppose that the ball and block are actually located on the top of a frictionless track as shown on the right. What are the speeds of the ball and block at the bottom of the hill (labeled as point B) and the top of the loop-the-loop (labeled as point C)?



 $\Delta E_{AB} = \Delta K_{AB} + \Delta U_{gAB} + \Delta U_s = 0$   $\Delta E_{AB} = \left(\frac{1}{2}m_{total}v_B^2 - \frac{1}{2}m_{total}v_A^2\right) +$   $(m_{total}gy_B - m_{total}gy_A) = 0$  $v_B = \sqrt{v_A^2 + 2gy_a} = \sqrt{\left(2.97\frac{m}{s}\right)^2 + 2 \times 9.8\frac{m}{s^2} \times 4m} = 9.3\frac{m}{s}$ 

$$\begin{aligned} \Delta E_{BC} &= \Delta K_{BC} + \Delta U_{gBC} + \Delta U_s = 0\\ \Delta E_{BC} &= \left(\frac{1}{2}m_{total}v_C^2 - \frac{1}{2}m_{total}v_B^2\right) + \left(m_{total}gy_C - m_{total}gy_B\right) = 0\\ v_C &= \sqrt{v_B^2 - 2gy_C} = \sqrt{\left(9.3\frac{m}{s}\right)^2 - 2 \times 9.8\frac{m}{s^2} \times 2m} = 6.9\frac{m}{s} \end{aligned}$$

d. What is the difference between the magnitudes of the reaction forces of the track at point B and point C?

At point B:  

$$F_{NB} - F_W = 0 \rightarrow F_{NB} = m_{total}g = 5.05kg \times 9.8\frac{m}{s^2} = 49.5N$$

At point C:

$$-F_{NC} - F_{W} = -F_{N} - m_{total}g = -m_{total}\frac{v_{C}^{2}}{R}$$
$$F_{NC} = m_{total}\frac{v_{C}^{2}}{R} - m_{total}g = (0.05kg + 5kg)\left[\frac{\left(6.9\frac{m}{s}\right)^{2}}{1m} - 9.8\frac{m}{s^{2}}\right] = 190.1N$$

The difference is  $\Delta F = F_{NB} - F_{NC} = -140.6N$ 

e. Suppose that the entire track was not frictionless and further that you measure the speeds at the top of the hill (labeled point A) and at the top of the loop-the-loop (labeled point C). Can you determine the work done by friction between points A and C? You will earn zero credit for simply saying yes or no. You need to explain in complete sentences why you think you can or why you think you cannot determine the work done by friction between points A and C. There is no actual calculation required for this question.

Yes, you can determine the work done by friction since you know the initial and final speeds of the system and the heights through which the masses fell. Thus  $\Delta E = W_{fr} = \Delta K + \Delta U_g$ . The one thing you could not determine is the frictional force since we don't know the actual path taken by the masses.

## **Physics 110 Formulas**

Motion  
$$\Delta x = x_f - x_i$$
 $v_{avg} = \frac{\Delta x}{\Delta t}$  $a_{avg} = \frac{\Delta v}{\Delta t}$ Equations of Motion  
displacement:Uniform Circular Motion  
 $y_f = y_i + v_y t + \frac{1}{2}a_y t^2$   
 $v_f = v_i + a_x t$   
 $v_{j_f} = v_y + a_y t$ Uniform Circular Motion  
 $F_r = ma_r = m\frac{v^2}{r};$ Geometry /Algebravelocity: $\begin{cases} x_f = x_i + v_x t + \frac{1}{2}a_y t^2 \\ v_f = v_i + a_x t \\ v_{j_f} = v_{j_f} + a_y t \end{cases}$  $F_r = ma_r = m\frac{v^2}{r};$  $a_r = \frac{v^2}{r}$   
 $A = \pi^{r^2}$ Circles Triangles Spheres  
 $C = 2\pi r$   
 $A = \frac{1}{2}bh$  $A = 4\pi r^2$ velocity: $\begin{cases} v_{j_f} = v_{j_f} + a_x t \\ v_{j_f} = v_{j_f} + a_y t \end{cases}$  $F_G = G\frac{m_i m_2}{r^2}$ Quadratic equation :  $ax^2 + bx + c = 0,$   
whose solutions are given by :  $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$ VectorsUseful Constants

$$\begin{array}{l} \text{magnitude of a vector: } v = \left| \vec{v} \right| = \sqrt{v_x^2 + v_y^2} \\ \text{direction of a vector: } \phi = \tan^{-1} \left( \frac{v_y}{v_x} \right) \\ \end{array} \\ \begin{array}{l} g = 9.8 \frac{m_{s^2}}{s} \quad G = 6.67 \times 10^{-11} \frac{Nm^2}{kg^2} \\ N_A = 6.02 \times 10^{23} \frac{a \text{toms}}{mole} \quad k_B = 1.38 \times 10^{-23} \frac{1}{k} \\ \sigma = 5.67 \times 10^{-8} \frac{w_{m^2 K^4}}{s} \quad v_{sound} = 343 \frac{m_s}{s} \end{array}$$

Linear Momentum/Forces Work/Energy Heat  $\overrightarrow{p} = m \overrightarrow{v}$  $K_t = \frac{1}{2}mv^2$  $T_{c} = \frac{5}{9} [T_{F} - 32]$  $\vec{p}_f = \vec{p}_i + \vec{F} \Delta t$  $K_r = \frac{1}{2}I\omega^2$  $T_F = \frac{9}{5}T_C + 32$  $\vec{F} = m\vec{a}$  $L_{new} = L_{old} \left( 1 + \alpha \Delta T \right)$  $U_g = mgh$  $A_{new} = A_{old} \left( 1 + 2\alpha \Delta T \right)$  $\vec{F_s} = -k\vec{x}$  $U_s = \frac{1}{2}kx^2$  $V_{new} = V_{old} \left( 1 + \beta \Delta T \right) : \beta = 3\alpha$  $F_f = \mu F_N$  $W_T = FdCos\theta = \Delta E_T$  $PV = Nk_{B}T$  $W_R = \tau \theta = \Delta E_R$  $\frac{3}{2}k_BT = \frac{1}{2}mv^2$  $W_{net} = W_R + W_T = \Delta E_R + \Delta E_T$  $\Delta Q = mc\Delta T$  $\Delta E_{R} + \Delta E_{T} + \Delta U_{g} + \Delta U_{S} = 0$  $P_{C} = \frac{\Delta Q}{\Delta t} = \frac{kA}{L} \Delta T$  $\Delta E_{R} + \Delta E_{T} + \Delta U_{g} + \Delta U_{S} = -\Delta E_{diss}$  $P_{R} = \frac{\Delta Q}{\Delta T} = \varepsilon \sigma A \Delta T^{4}$ 

Rotational MotionFluidsSimple Harmonic Motion/Waves
$$\theta_f = \theta_i + \omega_i t + \frac{1}{2} \alpha t^2$$
 $\rho = \frac{M}{V}$  $\omega = 2\pi f = \frac{2\pi}{T}$  $\omega_f = \omega_i + \alpha t$  $\rho = \frac{F}{A}$  $\omega = 2\pi f = \frac{2\pi}{T}$  $\omega^2_f = \omega^2_i + 2\alpha\Delta\theta$  $P = \frac{F}{A}$  $T_s = 2\pi \sqrt{\frac{R}{k}}$  $\tau = I\alpha = rF$  $P_d = P_0 + \rho g d$  $T_p = 2\pi \sqrt{\frac{I}{g}}$  $L = I\omega$  $F_B = \rho g V$  $v = t\sqrt{\frac{K}{m}} A \left(1 - \frac{x^2}{A^2}\right)^{\frac{1}{2}}$  $\Delta s = r\Delta\theta$ :  $v = r\omega$ :  $a_t = r\alpha$  $\rho_1 A_1 v_1 = \rho_2 A_2 v_2$  $v = t\sqrt{\frac{K}{m}} A \left(1 - \frac{x^2}{A^2}\right)^{\frac{1}{2}}$  $\Delta s = r\Delta\theta$ :  $v = r\omega$ :  $a_t = r\alpha$  $\rho_1 A_1 v_1 = \rho_2 A_2 v_2$  $x(t) = A \sin(\frac{2\pi}{T})$  $a_r = r\omega^2$  $P_1 + \frac{1}{2} \rho v^2_1 + \rho g h_1 = P_2 + \frac{1}{2} \rho v^2_2 + \rho g h_2$  $a(t) = -A \frac{K}{m} \sin(\frac{2\pi}{T})$  $v = f\lambda = (331 + 0.6T) \frac{m}{s}$  $v = f\lambda = \sqrt{\frac{F_r}{\mu}}$  $v = f\lambda = \sqrt{\frac{F_r}{\mu}}$ 

$$\beta = 10 \log \frac{I}{I_0}; \quad I_o = 1 \times 10^{-12} \frac{W}{m^2}$$
$$f_n = nf_1 = n \frac{V}{2L}; \quad f_n = nf_1 = n \frac{V}{4L}$$

 $f_n = nf_1 = n\frac{v}{2L}$  $I = 2\pi^2 f^2 \rho v A^2$ 

 $\frac{1}{2}$