Name $\qquad$
Physics 110 Quiz \#7, May 27, 2022
Please show all work, thoughts and/or reasoning in order to receive partial credit. The quiz is worth 10 points total.

I affirm that I have carried out my academic endeavors with full academic honesty.

Suppose that you are standing on a hill inclined at angle $\theta$ with respect to the ground. Your legs are separated by a distance $d$ with one foot uphill and one foot downhill. The center of your body (where your weight $F_{W}=m g$ acts) is at a heigh $h$ measured perpendicular to the hill as shown below. Assume that static friction is large enough under each foot that you don't slide down the hill.


1. Assuming the tilted coordinate system shown, what is the expression for the forces parallel to the hill.

$$
\begin{aligned}
& F_{f r, L}+F_{f r, R}-F_{w x}=F_{f r, L}+F_{f r, R}-m g \sin \theta=m a_{x}=0 \\
& \rightarrow F_{f r, L}+F_{f r, R}=m g \sin \theta
\end{aligned}
$$

2. What is the expression for the forces perpendicular to the hill?

$$
\begin{aligned}
& F_{N L}+F_{N R}-F_{w y}=F_{N L}+F_{N R}-m g \cos \theta=m a_{y}=0 \\
& \rightarrow F_{N L}+F_{N R}=m g \cos \theta
\end{aligned}
$$

3. Taking the pivot to be at the center of your body, what is the expression for the torques about your center if you are just on the verge of tipping and falling down the hill? Assume counterclockwise rotations are positive and clockwise rotations negative.

$$
\begin{aligned}
& -r_{L} F_{N L} \sin \beta+r_{L} F_{f r, L} \sin (90-\beta)+r_{R} F_{N R} \sin \beta+r_{R} F_{f r, R} \sin (90-\beta)=I \alpha=0 \\
& 0=-\frac{d}{2} F_{N L}+h F_{f r, L}+\frac{d}{2} F_{N R}+h F_{f r, R} \\
& \rightarrow\left(F_{N R}-F_{N L}\right) \frac{d}{2}+\left(F_{f r, L}+F_{f r, R}\right) h=0
\end{aligned}
$$

4. Suppose that $m=60 \mathrm{~kg}, d=0.85 \mathrm{~m}, h=0.7 \mathrm{~m}$, and $\theta=30^{\circ}$, what is the magnitude of the normal force on your left foot, $F_{N L}$ ?

$$
\begin{aligned}
& 0=\left[\left(m g \cos \theta-F_{N L}\right)-F_{N L}\right] \frac{d}{2}+(m g \sin \theta) h \\
& F_{N L}=\frac{m g \cos \theta}{2}+m g \frac{h}{d} \sin \theta=60 \mathrm{~kg} \times 9.8 \frac{m}{s^{2}}\left[\frac{\cos 30}{2}+\frac{0.7 m}{0.85 m} \sin 30\right] \\
& F_{N L}=497 N
\end{aligned}
$$

5. What is the magnitude of the normal force on your right foot, $F_{N R}$ ? Hint, $F_{N L}$ and $F_{N R}$ are not equal to each other in this case.

$$
\begin{aligned}
& F_{N R}=m g \cos \theta-F_{N L}=m g \cos \theta-\frac{m g \cos \theta}{2}-m g \frac{h}{d} \sin \theta \\
& F_{N R}=\frac{m g \cos \theta}{2}-m g \frac{h}{d} \sin \theta=60 \mathrm{~kg} \times 9.8 \frac{m}{s^{2}}\left[\frac{\cos 30}{2}-\frac{0.7 m}{0.85 m} \sin 30\right] \\
& F_{N R}=12 N
\end{aligned}
$$

Vectors
$v=\sqrt{v_{x}^{2}+v_{y}^{2}}$
$\phi=\tan ^{-1}\left(\frac{v_{y}}{v_{x}}\right)$

## Motion Definitions

Displacement: $\Delta x=x_{f}-x_{i}$
Average velocity: $v_{\text {avg }}=\frac{\Delta x}{\Delta t}$
Average acceleration: $a_{a v g}=\frac{\Delta v}{\Delta t}$

## Equations of Motion

displacement: $\left\{\begin{array}{l}x_{f}=x_{i}+v_{i x} t+\frac{1}{2} a_{x} t^{2} \\ y_{f}=y_{i}+v_{i y} t+\frac{1}{2} a_{y} t^{2}\end{array}\right.$
velocity: $\left\{\begin{array}{l}v_{f x}=v_{i x}+a_{x} t \\ v_{f y}=v_{i y}+a_{y} t\end{array}\right.$
time-independent: $\left\{\begin{array}{l}v_{f x}^{2}=v_{i x}^{2}+2 a_{x} \Delta x \\ v_{f y}^{2}=v_{i y}^{2}+2 a_{y} \Delta y\end{array}\right.$

Rotational Motion Definitions
Angular displacement: $\Delta s=r \Delta \theta$
Angular velocity: $\omega=\frac{\Delta \theta}{\Delta t} \rightarrow v=r \omega$
Angular acceleration: $\alpha=\frac{\Delta \omega}{\Delta t} \rightarrow\left\{\begin{array}{c}a_{t}=r \alpha \\ a_{c}=r \omega^{2}\end{array}\right.$
Rotational Equations of Motion

$$
\begin{aligned}
& \theta_{f}=\theta_{i}+\omega_{i} t+\frac{1}{2} \alpha t^{2} \\
& \omega_{f}=\omega_{i}+\alpha t \\
& \omega_{f}^{2}=\omega_{i}^{2}+2 \alpha \Delta \theta
\end{aligned}
$$

Momentum \& Force
$\vec{p}=m \vec{v} \rightarrow p_{x}=m v_{x} ; p_{y}=m v_{y}$
$\Delta \vec{p}=\vec{F} \Delta t \rightarrow \vec{p}_{f}=\vec{p}_{i}+\vec{F} \Delta t$
$\vec{F}=\frac{d \vec{p}}{d t}=m \vec{a} \rightarrow F_{x}=m a_{x} ; F_{y}=m a_{y}$
$F_{f r}=\mu F_{N}$
$F_{w}=m g$
$F_{S}=-k x$
$F_{G}=G \frac{M_{1} M_{2}}{r^{2}}$
$F_{c}=m a_{c}=m \frac{v^{2}}{R}$
Work \& Energy
$\left\{\begin{array}{c}W_{T}=\int \vec{F} \cdot d \vec{r}=F d r \cos \theta=\Delta K_{T} \\ W_{R}=\int \vec{\tau} \cdot d \vec{\theta}=\tau d \theta=\Delta K_{R}\end{array}\right.$
$W_{\text {net }}=W_{T}+W_{R}=\Delta K_{T}+\Delta K_{R}=-\Delta U$
$K_{T}=\frac{1}{2} m v^{2}$
$K_{R}=\frac{1}{2} I \omega^{2}$
$U_{g}=m g y$
$U_{s}=\frac{1}{2} k x^{2}$
$\Delta E=\Delta E_{R}+\Delta E_{T}$
$\Delta E=\Delta K_{R}+\Delta K_{T}+\Delta U_{g}+\Delta U_{s}=\left\{\begin{array}{c}0 \\ W_{f r}\end{array}\right.$
Rotational Momentum \& Force

$$
\begin{aligned}
& \vec{\tau}=\vec{r} \times \vec{F} ; \tau=r_{\perp} F=r F_{\perp}=r F \sin \theta \\
& \tau=\frac{\Delta L}{\Delta t}=I \alpha \\
& L=I \omega \\
& \Delta \vec{L}=\vec{\tau} \Delta t \rightarrow \vec{L}_{f}=\vec{L}_{i}+\vec{\tau} \Delta t
\end{aligned}
$$

$$
\begin{aligned}
& \rho=\frac{m}{V} \\
& P=\frac{F}{A} \\
& P_{y}=P_{\text {air }}+\rho g y \\
& F_{B}=\rho g V \\
& \rho_{1} A_{1} v_{1}=\rho_{2} A_{2} v_{2} ; \text { compressible } \\
& A_{1} v_{1}=A_{2} v_{2} ; \text { incompressible } \\
& P_{1}+\frac{1}{2} \rho v_{1}^{2}+\rho g y_{1}=P_{2}+\frac{1}{2} \rho v_{2}^{2}+\rho g y_{2} \\
& \text { Simple Harmonic Motion } \\
& \omega=2 \pi f=\frac{2 \pi}{T} \\
& T_{s}=2 \pi \sqrt{\frac{m}{k}} ; \quad \omega=\sqrt{\frac{k}{m}} \\
& T_{p}=2 \pi \sqrt{\frac{l}{g}} ; \quad \omega=\sqrt{\frac{g}{l}}
\end{aligned}
$$

Geometry/Algebra
Circles: $\quad A=\pi r^{2} \quad C=2 \pi r=\pi D$
Spheres: $\quad A=4 \pi r^{2} \quad V=\frac{4}{3} \pi r^{3} \quad a(t)=\left\{\begin{array}{l}-a_{\max } \sin \left(\frac{2 \pi}{T} t\right) \\ -a_{\max } \cos \left(\frac{2 \pi}{T} t\right)\end{array}\right.$
Triangles: $\quad A=\frac{1}{2} b h$
$v_{s}=f \lambda=(331+0.6 T) \frac{m}{s}$
$\beta=10 \log \frac{I}{I_{o}}$

Waves
$v=f \lambda=\sqrt{\frac{F_{T}}{\mu}}$
$f_{n}=n f_{1}=n \frac{v}{2 L} ; n=1,2,3, \ldots$
$I=2 \pi^{2} f^{2} \rho v A^{2}$

Equations of Motion for SHM

$$
v(t)=\left\{\begin{array}{c}
v_{\max } \cos \left(\frac{2 \pi}{T} t\right) \\
-v_{\max } \sin \left(\frac{2 \pi}{T} t\right)
\end{array}\right.
$$

Quadratics: $\quad a x^{2}+b x+c=0 \rightarrow x=\frac{-b \pm \sqrt{b^{2}-4 a c}}{2 a}$

$$
x(t)=\left\{\begin{array}{l}
x_{\max } \sin \left(\frac{2 \pi}{T} t\right) \\
x_{\max } \cos \left(\frac{2 \pi}{T} t\right)
\end{array}\right.
$$

Common Metric Prefixes
nano $=1 \times 10^{-9}$
micro $=1 \times 10^{-6}$
milli $=1 \times 10^{-3}$
centi $=1 \times 10^{-2}$
kilo $=1 \times 10^{3}$
$m e g a=1 \times 10^{6}$
$f_{n}=n f_{1}=n \frac{v}{2 L} ; n=1,2,3, \ldots$ open pipes
$f_{n}=n f_{1}=n \frac{v}{4 L} ; n=1,3,5, \ldots$ closed pipes

Periodic Table of the Elements


