

Name \_\_\_\_\_

Physics 120 Quiz #2, January 21, 2022

Please show all work, thoughts and/or reasoning in order to receive partial credit. The quiz is worth 10 points total.

I affirm that I have carried out my academic endeavors with full academic honesty.

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Suppose that a projectile was launched from the ground at a point  $\vec{r}_i = \langle 0, 0, 0 \rangle m$  with an initial velocity  $\vec{v}_i = \langle 8.7, 5.0, 0.0 \rangle \frac{m}{s}$ . For the questions below, ignore air resistance and assume a standard cartesian coordinate system with the positive x-direction to the right and the positive y-direction vertically up.

1. At what initial angle  $\theta$  measured with respect to the positive x-axis was the projectile launched and what was the launch speed,  $|\vec{v}_i|$ ?

$$\vec{v}_i = \langle v_{ix}, v_{iy}, v_{iz} \rangle = \langle 8.7, 5.0, 0 \rangle \frac{m}{s}$$

$$v_i = |\vec{v}_i| = \sqrt{v_{ix}^2 + v_{iy}^2 + v_{iz}^2} = \sqrt{\left(8.7 \frac{m}{s}\right)^2 + \left(5.0 \frac{m}{s}\right)^2 + \left(0 \frac{m}{s}\right)^2} = 10 \frac{m}{s}$$

$$\tan \theta = \frac{v_{fy}}{v_{fx}} \rightarrow \theta = \tan^{-1} \frac{v_{fy}}{v_{fx}} = \tan^{-1} \frac{5.0 \frac{m}{s}}{8.7 \frac{m}{s}} = 29.9^\circ$$

2. At what time(s) will the projectile be at a vertical height of  $y = 1m$ ?

$$\vec{r}_f = \vec{r}_i + \vec{v}_i t + \frac{1}{2} \vec{a} t^2 \rightarrow \langle x_f, y_f, z_f \rangle = \langle x_i + v_{ix} t + \frac{1}{2} a_x t^2, y_i + v_{iy} t + \frac{1}{2} a_y t^2, 0 \rangle$$

In the y-direction:

$$y_f = y_i + v_{iy} t + \frac{1}{2} a_y t^2 \rightarrow 1 = 5t - \frac{1}{2} (9.8) t^2 \rightarrow -4.9t^2 + 5t - 1 = 0$$

By the quadratic formula:  $t = \begin{cases} 0.27s \\ 0.75s \end{cases}$

Both times are acceptable. The time  $t = 0.27s$  is for the projectile rising and  $t = 0.75s$  is for the projectile falling.

3. What is the time of flight of the projectile? Assume that the projectile starts and ends on the ground.

$$\vec{r}_f = \vec{r}_i + \vec{v}_i t + \frac{1}{2} \vec{a} t^2 \rightarrow \langle x_f, y_f, z_f \rangle = \langle x_i + v_{ix} t + \frac{1}{2} a_x t^2, y_i + v_{iy} t + \frac{1}{2} a_y t^2, 0 \rangle$$

$$\text{In the y-direction: } y_f = y_i + v_{iy} t + \frac{1}{2} a_y t^2 \rightarrow 0 = 0 + v_{iy} t - \frac{1}{2} g t^2 \rightarrow \begin{cases} t = 0 \\ t = \frac{2v_{iy}}{g} \end{cases}$$

$$t = \frac{2v_{iy}}{g} = \frac{2 \times 5 \frac{m}{s}}{9.8 \frac{m}{s^2}} = 1.02s$$

4. How far horizontally does the projectile travel across the ground from its launch point to its landing point?

$$\text{In the x-direction: } x_f = x_i + v_{ix} t + \frac{1}{2} a_x t^2 = v_{ix} t = 8.7 \frac{m}{s} \times 1.02s = 8.9m$$

5. What is the impact velocity  $\vec{v}_f$  of the projectile just before striking the ground? That is, what are the components of the final velocity in  $\vec{v}_f = \langle v_{fx}, v_{fy}, v_{fz} \rangle$ .

$$\vec{v}_f = \vec{v}_i + \vec{a} t \rightarrow \langle v_{fx}, v_{fy}, v_{fz} \rangle = \langle v_{ix} + a_x t, v_{iy} + a_y t, 0 \rangle$$

$$\text{In the x-direction: } v_{fx} = v_{ix} = 8.7 \frac{m}{s}$$

$$\text{In the y-direction: } v_{fy} = v_{iy} - g t = 5 \frac{m}{s} - 9.8 \frac{m}{s^2} \times 1.02s = -5 \frac{m}{s}$$

$$\vec{v}_f = \langle v_{fx}, v_{fy}, v_{fz} \rangle = \langle 8.7, -5, 0 \rangle \frac{m}{s}$$

## Physics 120 Formula Sheet

### General Definitions of Motion

$$\Delta \vec{r} = \langle \Delta x, \Delta y, \Delta z \rangle = \langle x_f - x_i, y_f - y_i, z_f - z_i \rangle$$

$$\vec{v} = \frac{\Delta \vec{r}}{\Delta t} = \left\langle \frac{\Delta x}{\Delta t}, \frac{\Delta y}{\Delta t}, \frac{\Delta z}{\Delta t} \right\rangle$$

$$\vec{a} = \frac{\Delta \vec{v}}{\Delta t} = \left\langle \frac{\Delta v_x}{\Delta t}, \frac{\Delta v_y}{\Delta t}, \frac{\Delta v_z}{\Delta t} \right\rangle$$

$$d\vec{r} = \langle dx, dy, dz \rangle$$

$$\vec{v} = \langle v_x, v_y, v_z \rangle = \frac{d\vec{r}}{dt} = \left\langle \frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \right\rangle$$

$$\vec{a} = \langle a_x, a_y, a_z \rangle = \frac{d\vec{v}}{dt} = \left\langle \frac{dv_x}{dt}, \frac{dv_y}{dt}, \frac{dv_z}{dt} \right\rangle$$

### Motion with constant acceleration

$$\vec{r}_f = \vec{r}_i + \vec{v}_i t + \frac{1}{2} \vec{a} t^2 \rightarrow \langle x_f, y_f, z_f \rangle = \langle x_i + v_{ix} t + \frac{1}{2} a_x t^2, y_i + v_{iy} t + \frac{1}{2} a_y t^2, z_i + v_{iz} t + \frac{1}{2} a_z t^2 \rangle$$

$$\vec{v}_f = \vec{v}_i + \vec{a} t \rightarrow \langle v_{fx}, v_{fy}, v_{fz} \rangle = \langle v_{ix} + a_x t, v_{iy} + a_y t, v_{iz} + a_z t \rangle$$

### Forces/Momentum

$$\vec{p} = m\vec{v}$$

$$\vec{F}_{net} = \frac{d\vec{p}}{dt} = m\vec{a}$$

$$\vec{p}_f - \vec{p}_i = \int d\vec{p} = \int \vec{F}_{net} dt$$

$$\vec{J} = \int \vec{F}_{net} dt$$

$$\vec{F}_{net} = \vec{F}_{\parallel} + \vec{F}_{\perp} = \frac{d\vec{p}}{dt} \hat{p} + \vec{p} \frac{d\hat{p}}{dt} = m\vec{a}_{\parallel} + m\vec{a}_{\perp}$$

$$|\vec{F}_{\perp}| = m|\vec{a}_{\perp}| = m \frac{v^2}{r}$$

$$\vec{F}_G = G \frac{M_1 M_2}{r_{12}^2} \hat{r}_{12} \rightarrow |\vec{F}_G| = G \frac{M_1 M_2}{r_{12}^2}$$

$$\vec{F}_G = m\vec{g}; \quad \vec{g} = G \frac{M_{cb}}{(R_{cb} + h)^2} \hat{r}$$

$$|\vec{F}_{fr}| = \mu |\vec{F}_N|$$

$$\vec{F}_s = -k\Delta \vec{r}$$

### Geometry

$$C = 2\pi r \quad A_{circle} = \pi r^2; \quad A_{rect} = LW$$

$$A_{triangle} = \frac{1}{2}bh; \quad A_{sphere} = 4\pi r^2$$

$$V_{sphere} = \frac{4}{3}\pi r^3; \quad V_{cyl} = \pi r^2 h; \quad V_{cone} = \frac{1}{3}\pi r^2 h$$

### Constants

$$g = 9.8 \frac{m}{s^2}; \quad G = 6.67 \times 10^{-11} \frac{Nm^2}{kg^2}$$

$$v_{sound} = 343 \frac{m}{s}; \quad v_{light} = c = 3 \times 10^8 \frac{m}{s}$$

$$N_A = 6.02 \times 10^{23}$$

### Vectors

$$\vec{C} = \vec{A} + \vec{B} \rightarrow \langle C_x, C_y, C_z \rangle = \langle A_x + B_x, A_y + B_y, A_z + B_z \rangle + \langle C_x, C_y, C_z \rangle; \quad |\vec{C}| = \sqrt{C_x^2 + C_y^2 + C_z^2}$$

$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta = A_x B_x + A_y B_y + A_z B_z$$

$$\vec{A} \times \vec{B} = |\vec{A}| |\vec{B}| \sin \theta = \langle a_y b_z - b_y a_z, a_z b_x - b_z a_x, a_x b_y - b_x a_y \rangle$$

## Work and Energy

$$W_T = \int dW_T = \int \vec{F} \cdot d\vec{r} = \Delta K_T = \frac{1}{2}mv_f^2 - \frac{1}{2}mv_i^2 = \frac{p_f^2}{2m} - \frac{p_i^2}{2m}$$

$$W_R = \int dW_R = \int \vec{\tau} \cdot d\vec{\theta} = \Delta K_R = \frac{1}{2}I\omega_f^2 - \frac{1}{2}I\omega_i^2 = \frac{L_f^2}{2I} - \frac{L_i^2}{2I}$$

$$W_{net} = W_T + W_R = \Delta E_{sys} = \begin{cases} 0 \\ W_{fr} \end{cases}$$

$$W_{net} = -\sum \Delta U = \Delta K_T + \Delta K_R$$

$$U_g = mgy$$

$$U_s = \frac{1}{2}kx^2$$

## Rotational Motion

$$s = r\theta \rightarrow ds = rd\theta$$

$$\frac{ds}{dt} = r \frac{d\theta}{dt} \rightarrow v = r\omega; \quad \omega = \frac{d\theta}{dt}$$

$$a = \frac{dv}{dt} = r \frac{d\omega}{dt} = r\alpha; \quad \alpha = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$$

$$\theta_f = \theta_i + \omega_i t + \frac{1}{2}\alpha t^2$$

$$\omega_f = \omega_i + \alpha t$$

$$\omega_f^2 = \omega_i^2 + 2\alpha\Delta\theta$$

## Rotational Forces/Momentum

$$\vec{\tau} = \vec{r} \times \vec{F} = \frac{d\vec{L}}{dt} = I\vec{\alpha}$$

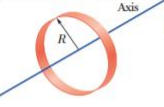
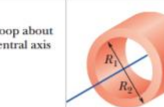
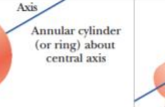
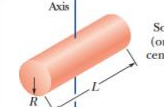
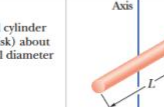
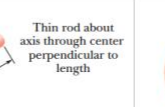
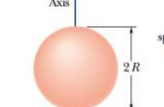
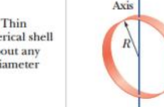
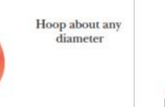
$$|\vec{\tau}| = rF \sin\theta = r_{\perp}F = rF_{\perp}$$

$$\vec{L} = I\vec{\omega}$$

$$I = \int r^2 dm$$

$$\vec{L}_f = \vec{L}_i + \int \vec{\tau}_{net} dt$$

Table 10-2 Some Rotational Inertias

|                                                                                                                                                                                                                 |                                                                                                                                                                                                            |                                                                                                                                                                                                       |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|  <p>Hoop about central axis</p> <p><math>I = MR^2</math></p> <p>(a)</p>                                                       |  <p>Annular cylinder (or ring) about central axis</p> <p><math>I = \frac{1}{2}M(R_1^2 + R_2^2)</math></p> <p>(b)</p>    |  <p>Solid cylinder (or disk) about central axis</p> <p><math>I = \frac{1}{2}MR^2</math></p> <p>(c)</p>            |
|  <p>Solid cylinder (or disk) about central diameter</p> <p><math>I = \frac{1}{4}MR^2 + \frac{1}{2}ML^2</math></p> <p>(d)</p> |  <p>Thin rod about axis through center perpendicular to length</p> <p><math>I = \frac{1}{12}ML^2</math></p> <p>(e)</p> |  <p>Solid sphere about any diameter</p> <p><math>I = \frac{2}{5}MR^2</math></p> <p>(f)</p>                       |
|  <p>Thin spherical shell about any diameter</p> <p><math>I = \frac{2}{3}MR^2</math></p> <p>(g)</p>                           |  <p>Hoop about any diameter</p> <p><math>I = \frac{1}{2}MR^2</math></p> <p>(h)</p>                                     |  <p>Slab about perpendicular axis through center</p> <p><math>I = \frac{1}{12}M(a^2 + b^2)</math></p> <p>(i)</p> |

Some moments of inertia from Halliday, Resnick, & Walker, 10<sup>th</sup> edition.