Name

Physics 110 Quiz #6, May 24, 2013 Please show all work, thoughts and/or reasoning in order to receive partial credit. The quiz is worth 10 points total.

I affirm that I have carried out my academic endeavors with full academic honesty.

The Union College Physics Department has decided to hang a sign outside of the department office so that all passers by can read how much fun physics can be. Suppose that the sign (with a mass $m_{sign} = 220kg$) is suspended by a massless wire from a uniform blue rod ($m_{rod} = 110kg$ and L = 2m) and that the blue rod makes an angle of $\theta = 30^{\circ}$ with respect to the vertical as shown below. The blue rod is attached to the wall by a horizontal massless support wire. The sign acts like a point mass ($I_{sign} = m_{sign}R^2$) and the blue rod is pivoted about one end ($I_{rod} = \frac{1}{3}m_{rod}R^2$)



a. Draw the reminder of the free-body diagram, by labeling the rest of the forces. The reaction force, F_R , of the pivot is given in the diagram. Then write down Newton's 2nd law in the horizontal and vertical directions and determine the tension in the horizontal support wire.

$$\sum F_{x}: F_{R}\sin\theta - F_{T} = 0 \to F_{T} = F_{R}\sin\theta = 3734.3N\sin 30 = 1867.2N$$
$$\sum F_{y}: F_{R}\cos\theta - m_{rod}g - m_{sign}g = 0 \to F_{R} = \frac{(m_{rod} + m_{sign})g}{\cos\theta} = \frac{(330kg \times 9.8\frac{m}{s^{2}})}{\cos 30} = 3734.3N$$

b. Write the expression for the sum of the torques about the pivot by choosing clockwise rotations as the positive direction for torque.

$$\sum \tau : \quad m_{rod} g \frac{L}{2} \sin \theta + m_{sign} g L \sin \theta - F_T R \sin(90 - \theta) = 0$$

c. How far from the pivot is the horizontal wire attached to the blue rod?

$$m_{rod}g\frac{L}{2}\sin\theta + m_{sign}gL\sin\theta - F_TR\sin(90-\theta) = 0$$

(110kg × 9.8 $\frac{m}{s^2}$ × 1m × sin 30) + (220kg × 9.8 $\frac{m}{s^2}$ × 2m × sin 30) - 1867.2N(R)sin 60 = 0
R = 1.67m

d. Suppose that the cable snaps and the system rotates about the pivot. What is the initial angular acceleration of the system about the pivot?

$$\sum \tau: \quad m_{rod}g \frac{L}{2}\sin\theta + m_{sign}gL\sin\theta = I\alpha = \left(\frac{1}{3}m_{rod}L^2 + m_{sign}L^2\right)\alpha$$
$$\alpha = \frac{m_{rod}g \frac{L}{2}\sin\theta + m_{sign}gL\sin\theta}{\left(\frac{1}{3}m_{rod}L^2 + m_{sign}L^2\right)} = \frac{\left(\frac{110kg}{2} + 220kg\right) \times 9.8\frac{m}{s^2} \times 2m \times \sin 30}{\left(\frac{110kg}{3} + 220kg\right) \times 4m^2} = 2.63\frac{rad}{s^2}$$

e. If the blue rod rotates from the initial angle of $\theta_i = 30^\circ$ to $\theta_f = 90^\circ$, work is done on the system. The torque is not constant, but changes with angle, and as the blue rod rotates through the 60° angle 3500*J* of work is done. If the system starts from rest, what is the angular velocity of the boom as it passes through the horizontal?

$$W_R = \Delta K E_R = \frac{1}{2} I \omega_f^2 \rightarrow \omega_f = \sqrt{\frac{2W_R}{\left(\frac{m_{rod}}{3} + m_{sign}\right)L^2}} = \sqrt{\frac{2 \times 3500J}{\left(\frac{110kg}{3} + 220kg\right)4m^2}} = 2.6 \frac{rad}{s}$$

Useful formulas:

Motion in the r = x, y or z-directions **Uniform Circular Motion Geometry** /Algebra $a_r = \frac{v^2}{r}$ $r_f = r_0 + v_{0r}t + \frac{1}{2}a_rt^2$ $\begin{array}{l} a_r = \frac{1}{r} \\ F_r = ma_r = m \frac{v^2}{r} \\ V = \frac{2\pi r}{T} \\ F_G = G \frac{m_1 m_2}{r^2} \\ \end{array}$ $\begin{array}{l} Circles \quad Triangles \quad Spheres \\ C = 2\pi r \quad A = \frac{1}{2}bh \quad A = 4\pi r^2 \\ A = \pi r^2 \\ V = \frac{4}{3}\pi r^3 \\ V = \frac{4}{3}\pi r^3 \\ V = \frac{4}{3}\pi r^3 \\ Quadratic \ equation : ax^2 + bx + c = 0, \\ F_G = G \frac{m_1 m_2}{r^2} \\ whose \ solutions \ are \ given \ by : x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \end{array}$ $v_{fr} = v_{0r} + a_r t$ $v_{fr}^{2} = v_{0r}^{2} + 2a_{r}\Delta r$

Vectors

 $\vec{p} = m\vec{v}$

 $\vec{F} = m\vec{a}$

 $\vec{F_s} = -k\vec{x}$ $F_f = \mu F_N$

magnitude of avector = $\sqrt{v_x^2 + v_y^2}$ direction of a vector $\rightarrow \phi = \tan^{-1} \left(\frac{v_y}{v_x} \right)$

$$g = 9.8 \frac{m}{s^2} \qquad G = 6.67 \times 10^{-11} \frac{Nm^2}{kg^2}$$
$$N_A = 6.02 \times 10^{23} \frac{atoms}{mole} \qquad k_B = 1.38 \times 10^{-23} \frac{J}{K}$$
$$\sigma = 5.67 \times 10^{-8} \frac{W}{m^2 K^4} \qquad v_{sound} = 343 \frac{m}{s}$$

Linear Momentum/ForcesWork/EnergyHeat
$$\vec{p} = \vec{m} \cdot \vec{v}$$
 $K_t = \frac{1}{2}mv^2$ $T_c = \frac{5}{9}[T_F - 32]$ $\vec{p}_f = \vec{p}_i + \vec{F} \Delta t$ $K_r = \frac{1}{2}I\omega^2$ $T_F = \frac{9}{5}T_c + 32$ $\vec{F} = m\vec{a}$ $U_g = mgh$ $L_{new} = L_{old}(1 + \alpha\Delta T)$ $\vec{F}_s = -k\vec{x}$ $U_S = \frac{1}{2}kx^2$ $A_{new} = A_{old}(1 + 2\alpha\Delta T)$ $\vec{F}_f = \mu F_N$ $W_T = FdCos\theta = \Delta E_T$ $V_{new} = V_{old}(1 + \beta\Delta T)$: $\beta = 3\alpha$ $W_R = \tau\theta = \Delta E_R$ $W_R = \tau\theta = \Delta E_R$ $PV = Nk_BT$ $W_{net} = W_R + W_T = \Delta E_R + \Delta E_T$ $\Delta Q = mc\Delta T$ $\Delta E_R + \Delta E_T + \Delta U_g + \Delta U_S = 0$ $\Delta Q = mc\Delta T$ $\Delta E_R + \Delta E_T + \Delta U_g + \Delta U_S = -\Delta E_{diss}$ $P_c = \frac{\Delta Q}{\Delta t} = \frac{kA}{L}\Delta T$ $P_R = \frac{\Delta Q}{\Delta T} = \varepsilon \sigma A \Delta T^4$

Useful Constants

$$\theta_{f} = \theta_{i} + \omega_{i}t + \frac{1}{2}\alpha t^{2}$$

$$\omega_{f} = \omega_{i} + \alpha t$$

$$\omega^{2}{}_{f} = \omega^{2}{}_{i} + 2\alpha\Delta\theta$$

$$\tau = I\alpha = rF$$

$$L = I\omega$$

$$L_{f} = L_{i} + \tau\Delta t$$

$$\Delta s = r\Delta\theta : v = r\omega : a_{i} = r\alpha$$

$$a_{r} = r\omega^{2}$$

Fluids

 $\rho = \frac{M}{V}$

 $P=\frac{F}{A}$

 $P_d = P_0 + \rho g d$ $F_B = \rho g V$ $A_1 v_1 = A_2 v_2$ $\rho_1 A_1 v_1 = \rho_2 A_2 v_2$

 $P_1 + \frac{1}{2}\rho v^2 + \rho gh_1 = P_2 + \frac{1}{2}\rho v^2 + \rho gh_2$

Sound

 $v = f\lambda = (331 + 0.6T)\frac{m}{s}$ $\beta = 10 \log \frac{I}{I_0}; \quad I_o = 1 \times 10^{-12} \frac{W}{m^2}$ $f_n = nf_1 = n\frac{v}{2L}; \ f_n = nf_1 = n\frac{v}{4L}$

$$\Delta U = \Delta Q - \Delta W$$

Simple Harmonic Motion/Waves

$$\omega = 2\pi f = \frac{2\pi}{T}$$

$$T_{S} = 2\pi \sqrt{\frac{h}{k}}$$

$$T_{P} = 2\pi \sqrt{\frac{l}{g}}$$

$$v = \pm \sqrt{\frac{k}{m}} A \left(1 - \frac{x^{2}}{A^{2}}\right)^{\frac{1}{2}}$$

$$x(t) = A \sin\left(\frac{2\pi}{T}\right)$$

$$v(t) = A \sqrt{\frac{k}{m}} \cos\left(\frac{2\pi}{T}\right)$$

$$a(t) = -A \frac{k}{m} \sin\left(\frac{2\pi}{T}\right)$$

$$v = f\lambda = \sqrt{\frac{F_{T}}{\mu}}$$

 $f_n = nf_1 = n\frac{1}{2L}$ $I = 2\pi^2 f^2 \rho v A^2$