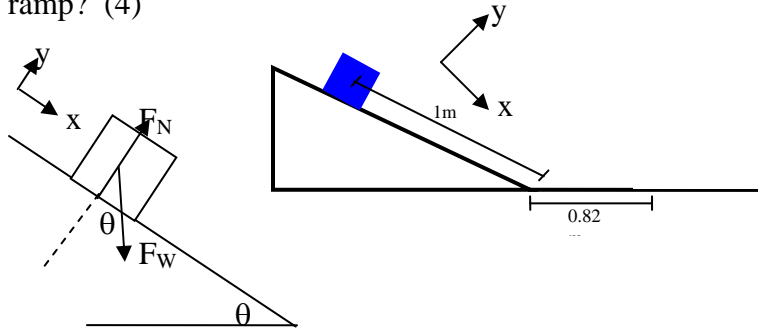


- 1a. A block of mass 2 kg initially located 1 m from the bottom of the frictionless ramp inclined at a 30° angle, as shown below. Using the coordinate system show, and from a carefully labeled free body diagram, what is the acceleration of the block along the ramp? (4)



$$\sum F_x : mg \sin \theta = ma_x \rightarrow a_x = g \sin \theta = 9.8 \frac{\text{m}}{\text{s}^2} \times \sin 30 = 4.9 \frac{\text{m}}{\text{s}^2}$$

$$\sum F_y : F_N - mg \cos \theta = ma_y = 0 \rightarrow F_N = mg \cos \theta$$

- 1b. If the block is *launched up the ramp* with an initial speed of 1.5 m/s , how far from the *bottom of the ramp* will it be when it stops rising? (2)

$$v_{fx}^2 = v_{ix}^2 + 2a_x \Delta x \rightarrow 0 = (-1.5 \frac{\text{m}}{\text{s}})^2 + 2 \times 4.9 \frac{\text{m}}{\text{s}^2} \times (-d) \rightarrow d = 0.23\text{m}$$

From bottom of ramp, distance = 1.23m .

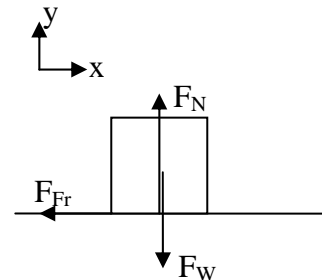
- 1c. If the speed of the block at the bottom of the ramp is 3.47 m/s and travels for 0.82 m along a rough patch along the ground ($\mu_k = 0.31$) what will be the speed of the block as it exits this rough patch? (Hint: You will need to draw a free body diagram for the block on the rough patch and calculate the acceleration of the block across the rough patch.) (4)

$$\sum F_x : -F_{Fr} = ma_x \rightarrow a_x = \frac{-F_{Fr}}{m} = \frac{-\mu_k F_N}{m} = \frac{-\mu_k mg}{m} = -\mu_k g = 0.31 \times 9.8 \frac{\text{m}}{\text{s}^2} = -3.04 \frac{\text{m}}{\text{s}^2}$$

$$\sum F_y : F_N - F_W = ma_y = 0 \rightarrow F_N = F_W = mg$$

$$v_{fx}^2 = v_{ix}^2 + 2a_x \Delta x \rightarrow 0 = (3.47 \frac{\text{m}}{\text{s}})^2 - 2 \times 3.04 \frac{\text{m}}{\text{s}^2} \times (0.82\text{m})$$

$$\therefore v_{fx} = 2.66 \frac{\text{m}}{\text{s}}$$



Useful formulas:**Motion in the x, y or z-directions**

$$r_f = r_0 + v_{0r}t + \frac{1}{2}a_r t^2$$

$$v_{fr} = v_{ir} + a_r t$$

$$v_{fr}^2 = v_{ir}^2 + 2a_r \Delta r$$

Vectors

$$\text{magnitude of a vector} = \sqrt{v_x^2 + v_y^2}$$

$$\text{direction of a vector} \rightarrow \phi = \tan^{-1}\left(\frac{v_y}{v_x}\right)$$

Linear Momentum/Forces

$$\vec{p} = m \vec{v}$$

$$\vec{p}_f = \vec{p}_i + \vec{F} \Delta t$$

$$\vec{F} = m \vec{a}$$

$$\vec{F}_s = -k \vec{x}$$

$$F_f = \mu F_N$$

Simple Harmonic Motion/Waves

$$\omega = 2\pi f = \frac{2\pi}{T}$$

$$T_s = 2\pi \sqrt{\frac{m}{k}}$$

$$T_p = 2\pi \sqrt{\frac{l}{g}}$$

$$v = \pm \sqrt{\frac{k}{m}} A \left(1 - \frac{x^2}{A^2}\right)^{\frac{1}{2}}$$

$$x(t) = A \sin\left(\frac{2\pi t}{T}\right)$$

$$v(t) = A \sqrt{\frac{k}{m}} \cos\left(\frac{2\pi t}{T}\right)$$

$$a(t) = -A \frac{k}{m} \sin\left(\frac{2\pi t}{T}\right)$$

$$v = f\lambda = \sqrt{\frac{F_T}{\mu}}$$

$$f_n = n f_1 = n \frac{v}{2L}$$

$$P = \frac{1}{2} \omega^2 \mu v A^2$$

Uniform Circular Motion

$$a_r = \frac{v^2}{r}$$

$$F_r = ma_r = m \frac{v^2}{r}$$

$$v = \frac{2\pi r}{T}$$

$$F_G = G \frac{m_1 m_2}{r^2}$$

Useful Constants

$$g = 9.8 \text{ m/s}^2 \quad G = 6.67 \times 10^{-11} \text{ Nm}^2/\text{kg}^2$$

$$N_A = 6.02 \times 10^{23} \text{ atoms/mole} \quad k_B = 1.38 \times 10^{-23} \text{ J/K}$$

$$\sigma = 5.67 \times 10^{-8} \text{ W/m}^2 \text{K}^4 \quad v_{\text{sound}} = 343 \text{ m/s} \quad P_{\text{air}} = 1.013 \times 10^5 \text{ N/m}^2$$

Work/Energy

$$K_t = \frac{1}{2} m v^2$$

$$K_r = \frac{1}{2} I \omega^2$$

$$U_g = mgh$$

$$U_s = \frac{1}{2} kx^2$$

$$W_T = Fd \cos \theta = \Delta E_T$$

$$W_R = \tau \theta = \Delta E_R$$

$$W_{\text{net}} = W_R + W_T = \Delta E_R + \Delta E_T$$

Geometry /Algebra

Circles Triangles Spheres

$$C = 2\pi r \quad A = \frac{1}{2}bh \quad A = 4\pi r^2$$

$$A = \pi r^2 \quad V = \frac{4}{3}\pi r^3$$

Quadratic equation: $ax^2 + bx + c = 0$,

$$\text{whose solutions are given by: } x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Rotational Motion

$$\theta_f = \theta_i + \omega_i t + \frac{1}{2} \alpha t^2$$

$$\omega_f = \omega_i + \alpha t$$

$$\omega_f^2 = \omega_i^2 + 2\alpha \Delta \theta$$

$$\tau = I\alpha = rF$$

$$L = I\omega$$

$$\Delta s = r\Delta \theta: v = r\omega: a_t = r\alpha$$

$$a_r = r\omega^2$$