

Name \_\_\_\_\_  
Physics 120 Quiz #7, March 9, 2007

1. A 50g object connected to a spring with a force constant of 35 N/m oscillates on a horizontal frictionless surface with amplitude 4cm.

a. What is the total energy of the system?

$$E_T = \frac{1}{2}kA^2 = \frac{1}{2}(35 \frac{N}{m})(0.04m)^2 = 0.028J$$

b. What is the speed of the object when the position is 1cm?

$$\frac{1}{2}kA^2 = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 \rightarrow v = \sqrt{\frac{kA^2}{m} \left(1 - \left(\frac{x}{A}\right)^2\right)}$$
$$v = \sqrt{\frac{35 \frac{N}{m} \times (0.04)^2}{0.05kg} \left(1 - \left(\frac{0.01m}{0.04m}\right)^2\right)} = 1.03 \frac{m}{s}$$

c. What is the kinetic energy when the position is 3 cm?

$$\frac{1}{2}kA^2 = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 \rightarrow v = \sqrt{\frac{kA^2}{m} \left(1 - \left(\frac{x}{A}\right)^2\right)}$$
$$v = \sqrt{\frac{35 \frac{N}{m} \times (0.04)^2}{0.05kg} \left(1 - \left(\frac{0.03m}{0.04m}\right)^2\right)} = 0.7 \frac{m}{s}$$
$$\therefore KE = \frac{1}{2}mv^2 = \frac{1}{2}(0.05kg)\left(0.7 \frac{m}{s}\right)^2 = 0.012J$$

d. What is the potential energy when the position is 3cm?

$$U_s = \frac{1}{2}kx^2 = \frac{1}{2}(35 \frac{N}{m})(0.03m)^2 = 0.016J$$

2. A sinusoidal wave of frequency  $f$  is traveling along a stretched string. The string is brought to rest and a second traveling wave of frequency  $\frac{3}{2}f$  is established on the same string. The wave speed of the second wave is

- a. slower than the first wave by a factor of  $\frac{2}{3}$ .
- b. faster than the first wave by a factor of  $\frac{2}{3}$ .
- c. the same as that of the first wave.
- d. unable to be determined.

**Motion in the x-direction**

$$x_f = x_i + v_{ix}t + \frac{1}{2}a_x t^2$$

$$v_{fx} = v_{ix} + a_x t$$

$$v_{fx}^2 = v_{ix}^2 + 2a_x \Delta x$$

$$F_x = ma_x$$

**Vectors**

$$\text{magnitude of a vector} = \sqrt{v_x^2 + v_y^2}$$

$$\text{direction of a vector} \rightarrow \phi = \tan^{-1}\left(\frac{v_y}{v_x}\right)$$

**Forces**

$$\vec{F} = m\vec{a} = \frac{d\vec{p}}{dt}$$

$$\vec{F}_s = -k\Delta\vec{x}$$

$$F_c = m\frac{v^2}{r}$$

**Relativity**

$$L = \frac{L_p}{\gamma}$$

$$\Delta t = \gamma\Delta t_p$$

$$p = \gamma mv$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$E_r = mc^2$$

$$E^2 = p^2 c^2 + m^2 c^4 = (\gamma mc^2)^2$$

$$KE = (\gamma - 1)mc^2$$

**Oscillatory Motion**

$$\frac{\partial^2 y}{\partial t^2} = -\omega^2 y; \quad \frac{\partial^2 \theta}{\partial t^2} = -\omega^2 \theta$$

$$\frac{d^2 x}{dt^2} = -\omega^2 x \rightarrow x(t) = A \cos(\omega t) \text{ or } x(t) = A \sin(\omega t)$$

$$v(t) = -A\omega \sin(\omega t) \text{ or } v(t) = A\omega \cos(\omega t); \quad v_{\max} = \omega A$$

$$a(t) = -A\omega^2 \cos(\omega t) \text{ or } a(t) = -A\omega^2 \sin(\omega t); \quad a_{\max} = \omega^2 A$$

$$\omega = 2\pi f; \quad T = \frac{1}{f}; \quad T_{\text{mass on a spring}} = 2\pi\sqrt{\frac{m}{k}}; \quad T_{\text{simple pendulum}} = 2\pi\sqrt{\frac{l}{g}}$$

**Motion in the y-direction**

$$y_f = y_i + v_{iy}t + \frac{1}{2}a_y t^2$$

$$v_{fy} = v_{iy} + a_y t$$

$$v_{fy}^2 = v_{iy}^2 + 2a_y \Delta y$$

$$F_y = ma_y$$

**Useful Constants**

$$g = 9.8 \frac{m}{s^2}$$

$$\text{Quadratic Equation : } ax^2 + bx + c = 0; \quad \text{solutions : } x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

**Work - Energy-Momentum**

$$W = \int_{i_1}^{i_2} \vec{F} \cdot d\vec{r} = \Delta KE$$

$$KE = \frac{1}{2}mv^2$$

$$PE_g = mgy$$

$$PE_s = \frac{1}{2}kx^2$$

$$\vec{p} = m\vec{v}$$

$$\vec{I} = \int \vec{F} dt = \Delta \vec{p}$$

**Rotational Motion**

$$s = r\theta; \quad v = r\omega; \quad a_t = r\alpha$$

$$\theta_f = \theta_i + \omega_i t + \frac{1}{2}\alpha t^2$$

$$\omega_f = \omega_i + \alpha t$$

$$\omega_f^2 = \omega_i^2 + 2\alpha\Delta\theta$$

$$|\vec{\tau}| = I\alpha = rF \sin \theta = \left| \frac{d\vec{L}}{dt} \right|$$

$$\vec{L} = I\vec{\omega}$$

$$KE_{rot} = \frac{1}{2}I\omega^2$$

**Simple Harmonic Motion/Mechanical Waves**

$$y = A \sin(kx - \omega t + \phi)$$

$$v = \frac{\omega}{k} = f\lambda = \sqrt{\frac{F_T}{\mu}}; \quad k = \frac{2\pi}{\lambda}$$

$$y = 2A \cos\left(\frac{\phi}{2}\right) \sin\left(kx - \omega t + \frac{\phi}{2}\right)$$

$$y = 2A \cos(\omega t) \sin(kx)$$

$$f_n = \frac{v}{\lambda_n} = \frac{n}{2L}v$$