

Physics 120 Formula Sheet

$$\bar{v}_x = \frac{\Delta x}{\Delta t} = \frac{x_f - x_i}{t_f - t_i} \quad v_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt} \quad \bar{a}_x = \frac{v_{xf} - v_{xi}}{t_f - t_i} = \frac{\Delta v_x}{\Delta t} \quad a_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta v}{\Delta t} = \frac{dv}{dt}$$

$$v_{xf} = v_{xi} + a_x t \quad x_f = x_i + \frac{1}{2}(v_{xi} + v_{xf})t \quad x_f = x_i + v_{xi}t + \frac{1}{2}a_x t^2 \quad v_{xf}^2 = v_{xi}^2 + 2a_x(x_f - x_i)$$

$$\Sigma \vec{F} = m\vec{a} \quad F_g = mg \quad \vec{F}_{12} = -\vec{F}_{21} \quad f_s \leq \mu_s n \quad f_k = \mu_k n \quad \vec{A} = A_x \hat{i} + A_y \hat{j}$$

$$A = \sqrt{A_x^2 + A_y^2} \quad \tan \theta = \frac{A_y}{A_x} \quad a_c = \frac{v^2}{r} \quad \vec{A} \cdot \vec{B} = AB \cos \theta = A_x B_x + A_y B_y + A_z B_z$$

$$W_{net} = \int_{r_1}^{r_2} (\Sigma \vec{F}) \cdot d\vec{r} \quad F_s = -kx \quad K = \frac{1}{2}mv^2 \quad W_{net} = K_f - K_i = \Delta K \quad g = 9.8 \text{ m/s}^2$$

$$\Delta E_{system} = \Sigma H \quad \Delta K = -f_k \Delta x + \Sigma W_{other \text{ forces}} \quad \Delta E_{int} = f_k \Delta x \quad P = \frac{dE}{dt} \quad U_g \equiv mgy$$

$$K_i + U_i = K_f + U_f \quad E_{mech} \equiv K + U \quad U_s \equiv \frac{1}{2}kx^2 \quad K + U + E_{int} = \text{constant} \quad U_f = - \int_{x_i}^{x_f} F_x dx + U_i$$

$$F_x = -\frac{dU}{dx} \quad \vec{p} = m\vec{v} \quad \Sigma \vec{F} = \frac{d\vec{p}}{dt} \quad \vec{I} \equiv \int_{t_i}^{t_f} \Sigma \vec{F} dt = \Delta \vec{p} \quad \vec{r}_{cm} = \frac{\Sigma_i m_i \vec{r}_i}{M}$$

$$\Delta t = \frac{\Delta t_p}{\sqrt{1 - \frac{v^2}{c^2}}} = \gamma \Delta t_p \quad L = \frac{L_p}{\gamma} = L_p \left(1 - \frac{v^2}{c^2}\right)^{\frac{1}{2}} \quad \vec{p} \equiv \frac{m\vec{u}}{\sqrt{1 - \frac{u^2}{c^2}}} \quad E_R = mc^2 \quad E = \frac{mc^2}{\sqrt{1 - \frac{u^2}{c^2}}}$$

$$K = \frac{mc^2}{\sqrt{1 - \frac{u^2}{c^2}}} - mc^2 = \gamma mc^2 - mc^2 = (\gamma - 1)mc^2 \quad E^2 = p^2 c^2 + (mc^2)^2 \quad \theta = \frac{s}{r} \quad \bar{\omega} = \frac{\theta_f - \theta_i}{t_f - t_i} = \frac{\Delta \theta}{\Delta t}$$

$$\omega = \lim_{\Delta t \rightarrow 0} \frac{\Delta \theta}{\Delta t} = \frac{d\theta}{dt} \quad \bar{\alpha} = \frac{\omega_f - \omega_i}{t_f - t_i} = \frac{\Delta \omega}{\Delta t} \quad \alpha = \lim_{\Delta t \rightarrow 0} \frac{\Delta \omega}{\Delta t} = \frac{d\omega}{dt} \quad \omega_f = \omega_i + \alpha t \quad v = r\omega \quad a_t = r\alpha$$

$$\theta_f = \theta_i + \omega_i t + \frac{1}{2} \alpha t^2 \quad \theta_f = \theta_i + \frac{1}{2} (\omega_i + \omega_f) t \quad \omega_f^2 = \omega_i^2 + 2\alpha (\theta_f - \theta_i) \quad a_c = \frac{v^2}{r} = r\omega^2$$

$$I = \sum_i m_i r_i^2 \quad K_R = \frac{1}{2} I \omega^2 \quad \vec{\tau} = \vec{r} \times \vec{F} \quad |\vec{A} \times \vec{B}| = AB \sin \theta \quad \Sigma \tau = I \alpha$$

$$\vec{L} = \vec{r} \times \vec{p} \quad L = mvr \sin \phi \quad \Sigma \vec{\tau}_{ext} = \frac{d\vec{L}}{dt} \quad \vec{L}_{tot,i} = \vec{L}_{tot,f}$$

$$x = A \cos(\omega t + \phi) \quad T = \frac{1}{f} = \frac{2\pi}{\omega} \quad \omega = \sqrt{\frac{k}{m}} \quad E = \frac{1}{2} k A^2 \quad T = 2\pi \sqrt{\frac{L}{g}}$$

$$y = A \sin \left[\frac{2\pi}{\lambda} (x - vt) \right] = A \sin(kx - \omega t) \quad v = \frac{\lambda}{T} = \lambda f \quad k \equiv \frac{2\pi}{\lambda} \quad \omega \equiv \frac{2\pi}{T} = 2\pi f$$

$$v = \sqrt{\frac{T}{\mu}} \quad y = (2A \sin kx) \cos \omega t \quad f_n = \frac{n}{2L} \sqrt{\frac{T}{\mu}} \quad (n = 1, 2, 3, \dots)$$