

Lecture 1: Strain Gauges

0. Course Intro

1. Strain

2. Strain Gauge

3. Strain Measurement

- Course website: minerva.union.edu/bumat

- Reading: Page 1-4 of Strain Gauge Tutorial pdf

- NO LAB THIS WEEK!

- PreLab 1 due at lab session (Jan 14/16)

- HW 1 due next Thu (Jan 16)

- Office Hours: Mon 2-4 PM
Wed 9-11 AM

} You are welcome to swing by
at other times, but I
may not be available!

or appointment (set up by email)

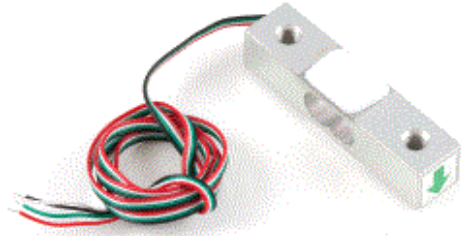
↑ bumat@union.edu

0. Course Intro

★ Course website: minerva.union.edu/bumat

- The lectures and labs for this course will concentrate on:

① Strain sensors
(e.g. load cells)



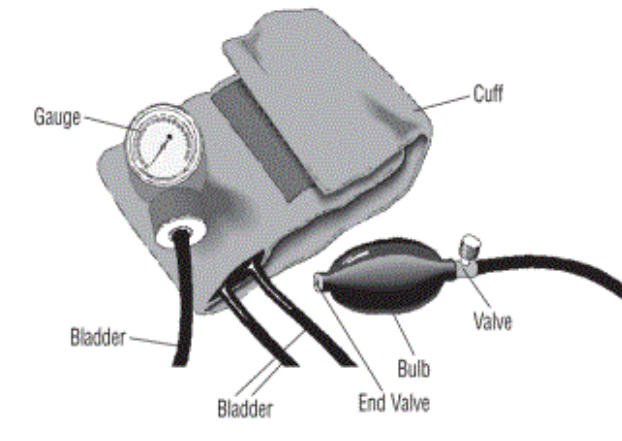
④ optical heart rate monitor



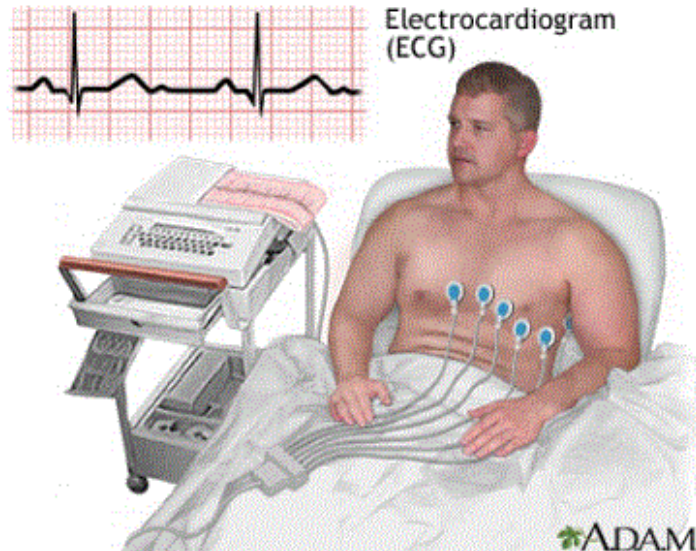
② Temperature
(e.g. thermistor)



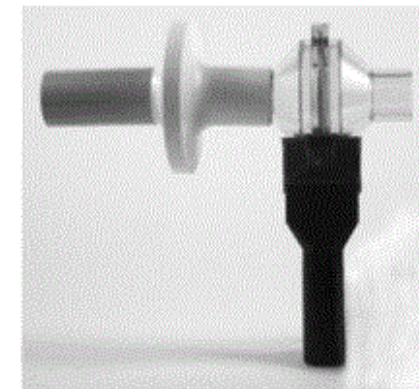
⑤ Blood pressure
(e.g. sphygmomanometer)



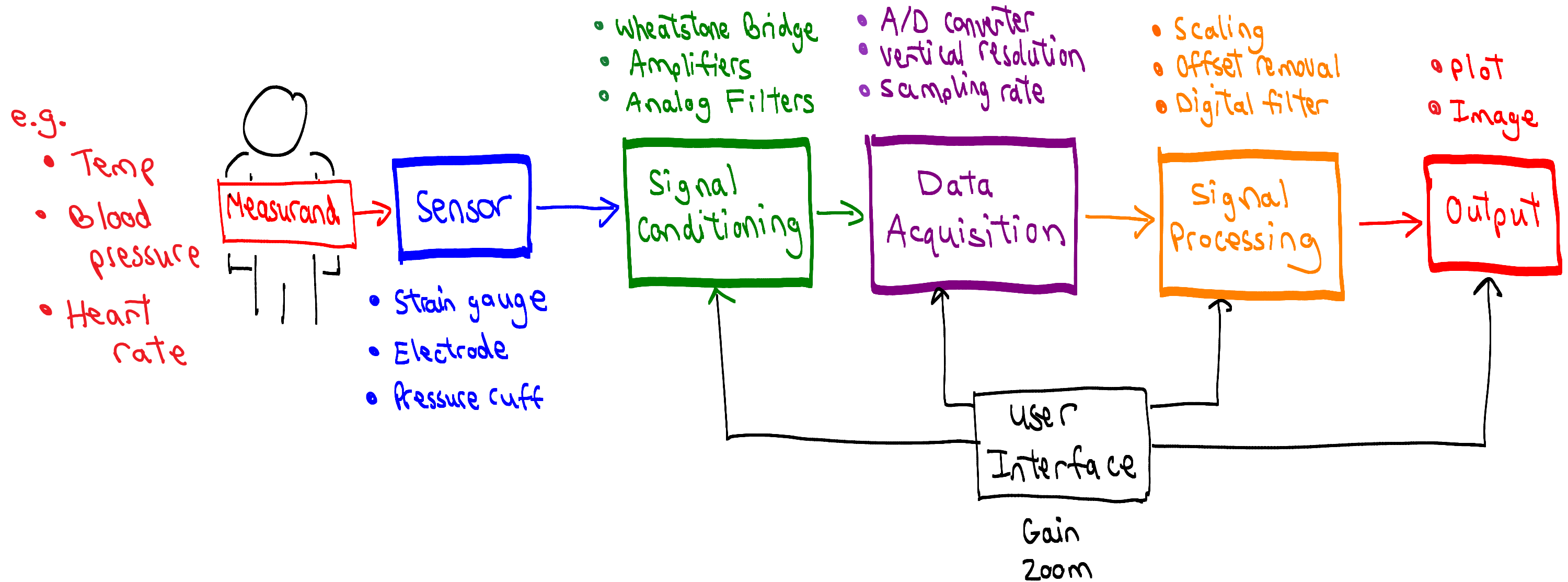
③ ECG



⑥ Respiration
(e.g. spirometer)



• Typical System Diagram



1. Strain

A. Why measure strain?

Strain is the deformation (e.g. bending) of a material that is under a mechanical load.

[Experimental measurement]

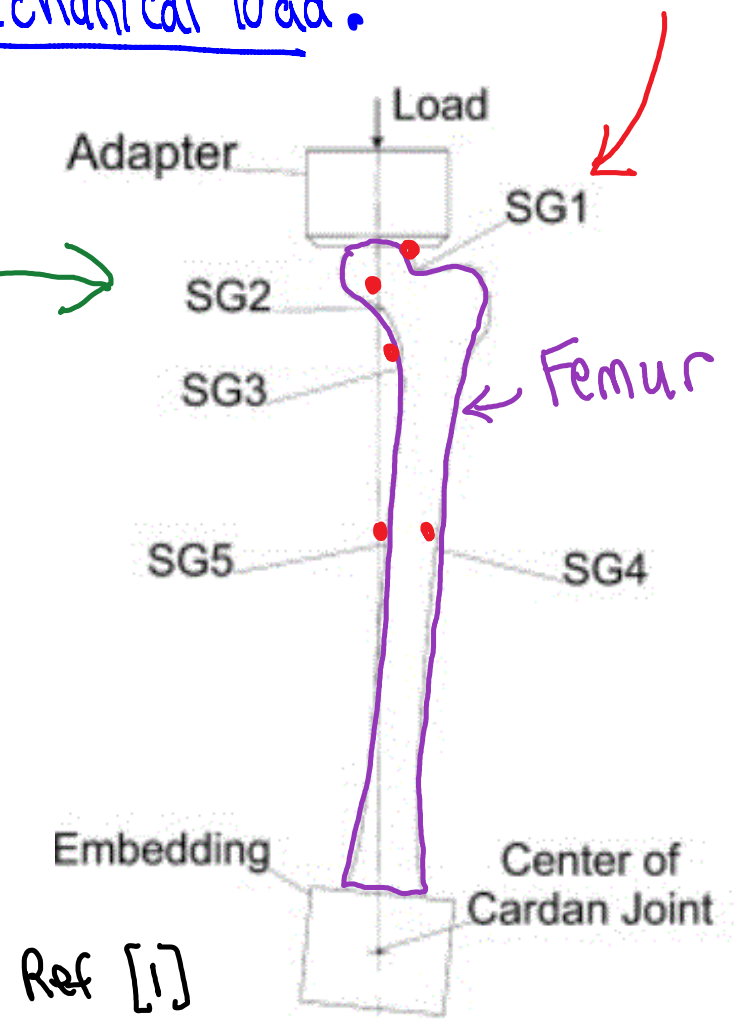
"SG" = Strain Gauge

[FEM model of strain]

[Mechanical Testing]

Example applications include.

- Bone mechanics
- Soft tissue mechanics
- Prosthesis materials
- Tissue engineering
- Materials testing



Ref [1]



Ref [2]

Stretched Sample



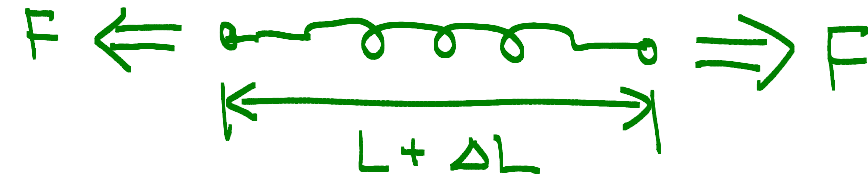
B. Stress-Strain Tutorial

• Hooke's Law :

For a spring,

$$F = k \Delta L$$

↖ spring constant



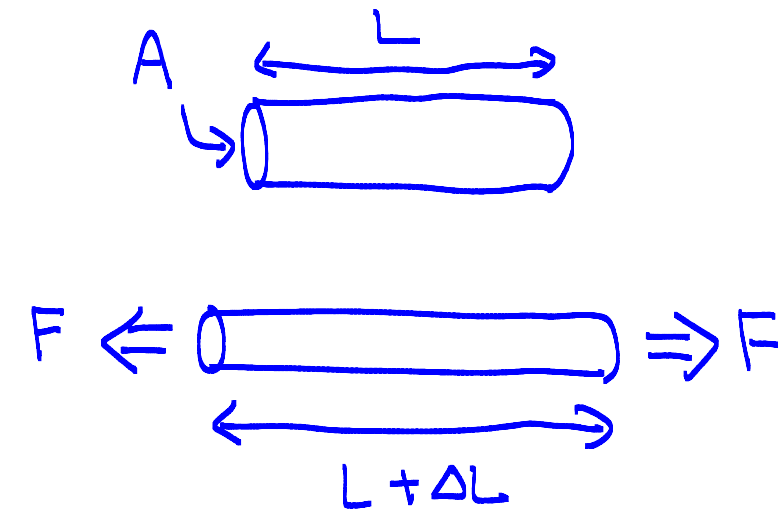
For a bulk material,

$$\sigma = E \epsilon$$

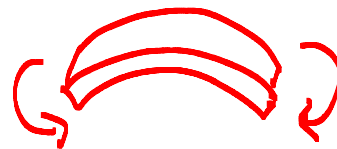
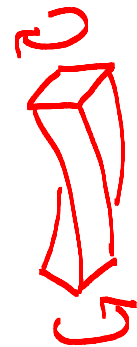
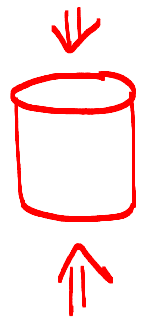
↖ Stress ↖ Elastic Modulus ↖ strain

Example: Tensile Strain $\frac{\Delta L}{L}$

$$\frac{F}{A} = E \frac{\Delta L}{L}$$



- Strain can also be compressive, shear, torsional, flexural, ...

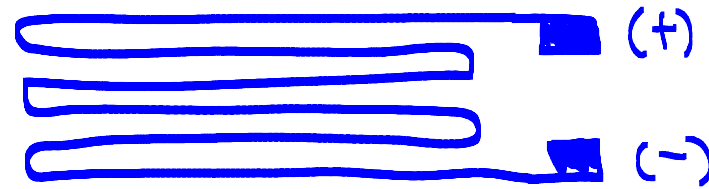
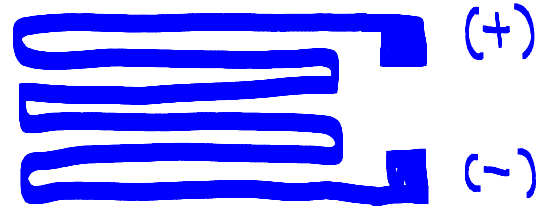


Q: How to measure strain?
→ Strain gauge!

2. Strain Gauge

When a thin wire is stretched,
its electrical resistance increases.

(no strain)

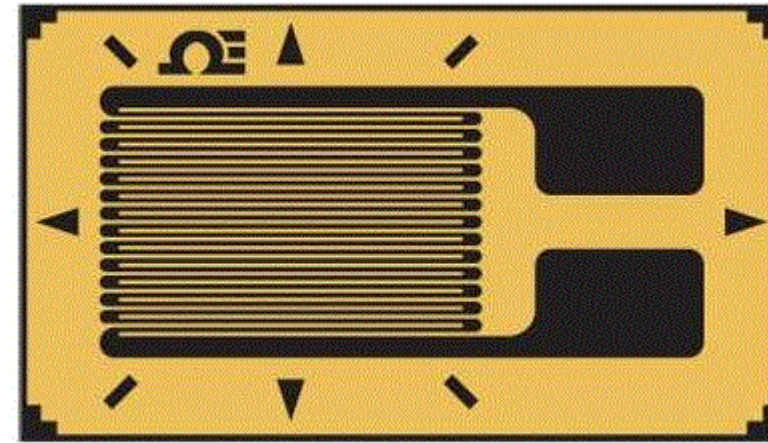


(Tensile strain)

www.omega.com

Ref [3]

(1.3)



Few mm

⇒ strain dependent resistor!

$$\frac{\Delta R}{R} = G \epsilon$$

Gauge
Factor

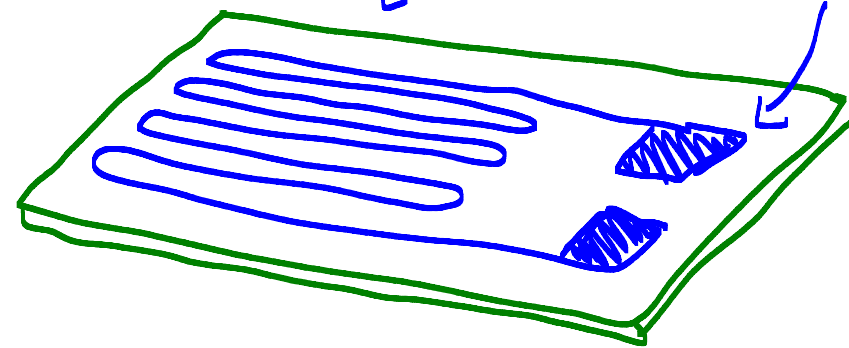
→ $\epsilon > 0$ (Tension)

→ $\epsilon < 0$ (compression)

NOTE: Typical $\epsilon \sim 10^{-6}$ (microstrain)
in solid materials

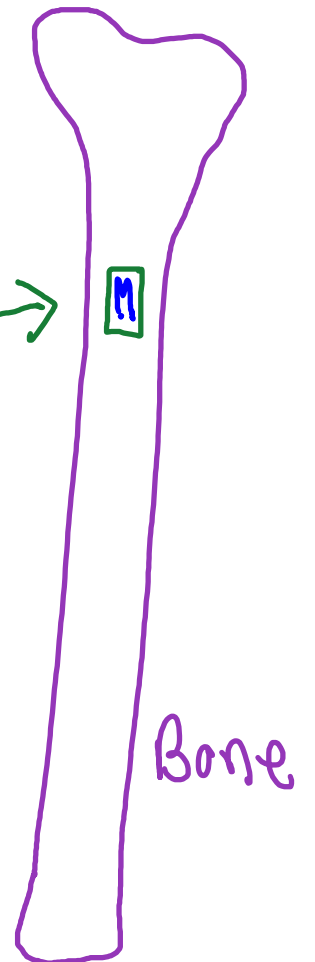
⇒ $\frac{\Delta R}{R}$ is tiny!

~25 μm
thick
plastic
substrate



~5 μm thick metal
foil pattern

Solder Pad



Bone

- Derivation of $\frac{\Delta R}{R} = G \epsilon$: $R = \rho \frac{L}{A}$ resistivity

$$\Delta R = \frac{\partial R}{\partial L} \Delta L + \frac{\partial R}{\partial A} \Delta A + \frac{\partial R}{\partial \rho} \Delta \rho$$

$$= \frac{\rho}{A} \Delta L - \rho \frac{L}{A^2} \Delta A + \frac{L}{A} \Delta \rho$$

$$= \frac{\rho L}{A} \left[\frac{\Delta L}{L} - \frac{\Delta A}{A} + \frac{\Delta \rho}{\rho} \right]$$

R →

Dimensional
Effect

↑ Piezoresistive
Effect

$$\frac{\Delta R}{R} =$$

Poisson Ratio

$$\frac{\Delta L}{L} + 2\mu \frac{\Delta L}{L} + \frac{\Delta \rho}{\rho}$$

$$= \left[1 + 2\mu + \frac{\Delta \rho / \rho}{\Delta L / L} \right] \left[\frac{\Delta L}{L} \right] = G * \epsilon \checkmark$$

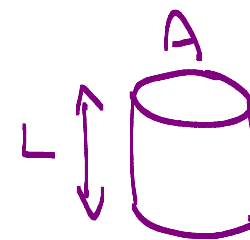
Significant
in semiconductors

↑ Gauge Factor

Ni/Cu alloy → Common metal is Constantan ($G=2.1$)

$$\frac{\Delta A}{A} = -2\mu \frac{\Delta L}{L}$$

↑ Poisson Ratio



$A + \Delta A$

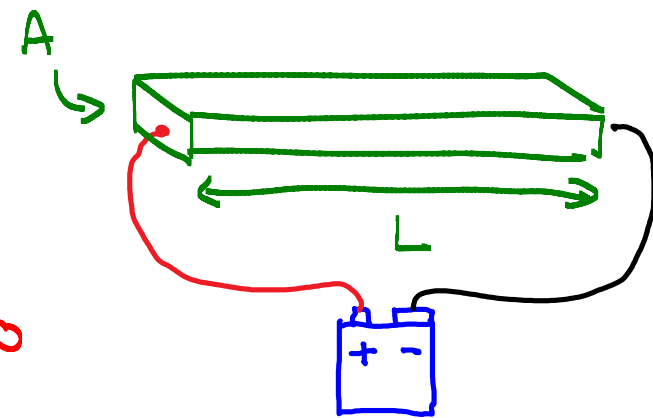
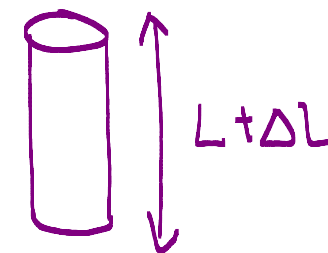
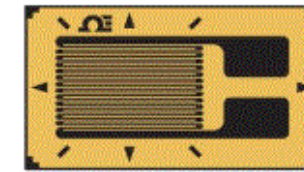


Table 2.1 Properties of Strain-Gage Materials

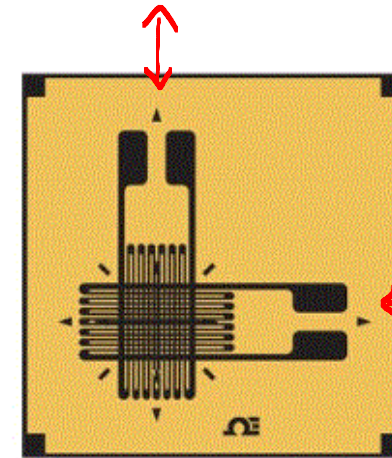
Material	Composition (%)	Gage Factor	Temperature Coefficient of Resistivity ($^{\circ}\text{C}^{-1} - 10^{-5}$)
★ Constantan (advance)	Ni ₄₅ , Cu ₅₅	2.1	± 2
Isoelastic	Ni ₃₆ , Cr ₈ (Mn, Si, Mo) ₄	3.52 to 3.6	+17
Karma	Fe ₅₂ Ni ₇₄ , Cr ₂₀ , Fe ₃ Cu ₃	2.1	+2
Manganin	Cu ₈₄ , Mn ₁₂ , Ni ₄	0.3 to 0.47	± 2
Alloy 479	Pt ₉₂ , W ₈	3.6 to 4.4	+24
Nickel	Pure	-12 to -20	670
Nichrome V	Ni ₈₀ , Cr ₂₀	2.1 to 2.63	10
Silicon	(<i>p</i> type)	100 to 170	70 to 700
Silicon	(<i>n</i> type)	-100 to -140	70 to 700
Germanium	(<i>p</i> type)	102	
Germanium	(<i>n</i> type)	-150	

Single
Axis
(uni-axial)

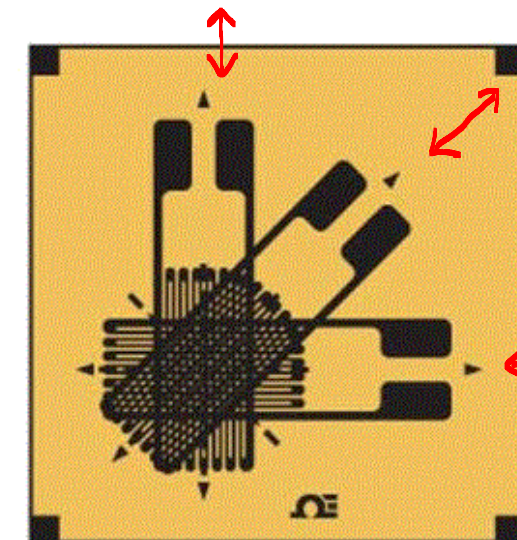


(1.5)

Biaxial



Rosette



Ref [3]

www.omega.com

Membrane-type
pressure sensors

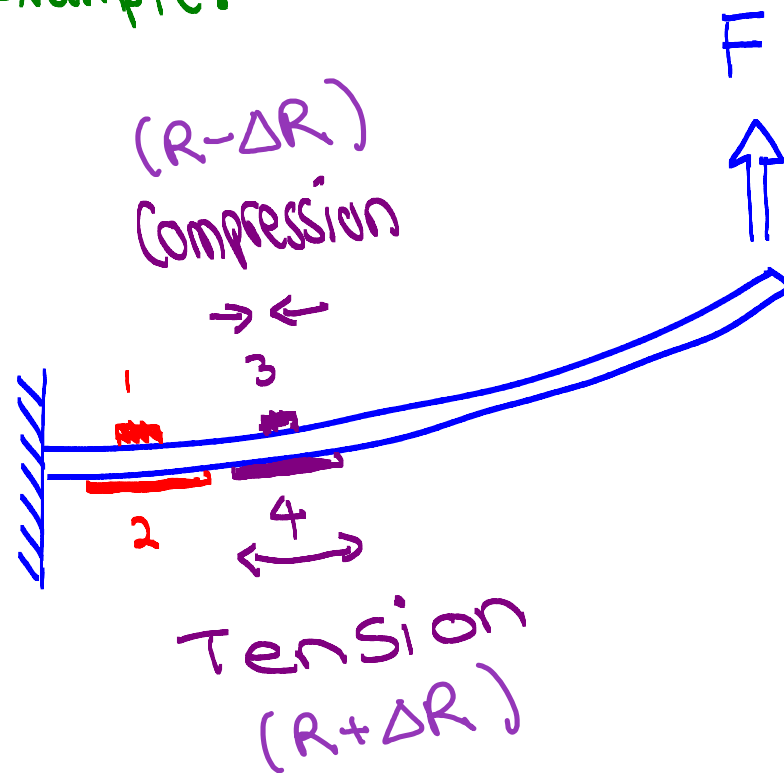
Strong
piezoresistive
effect

3. Signal Conditioning

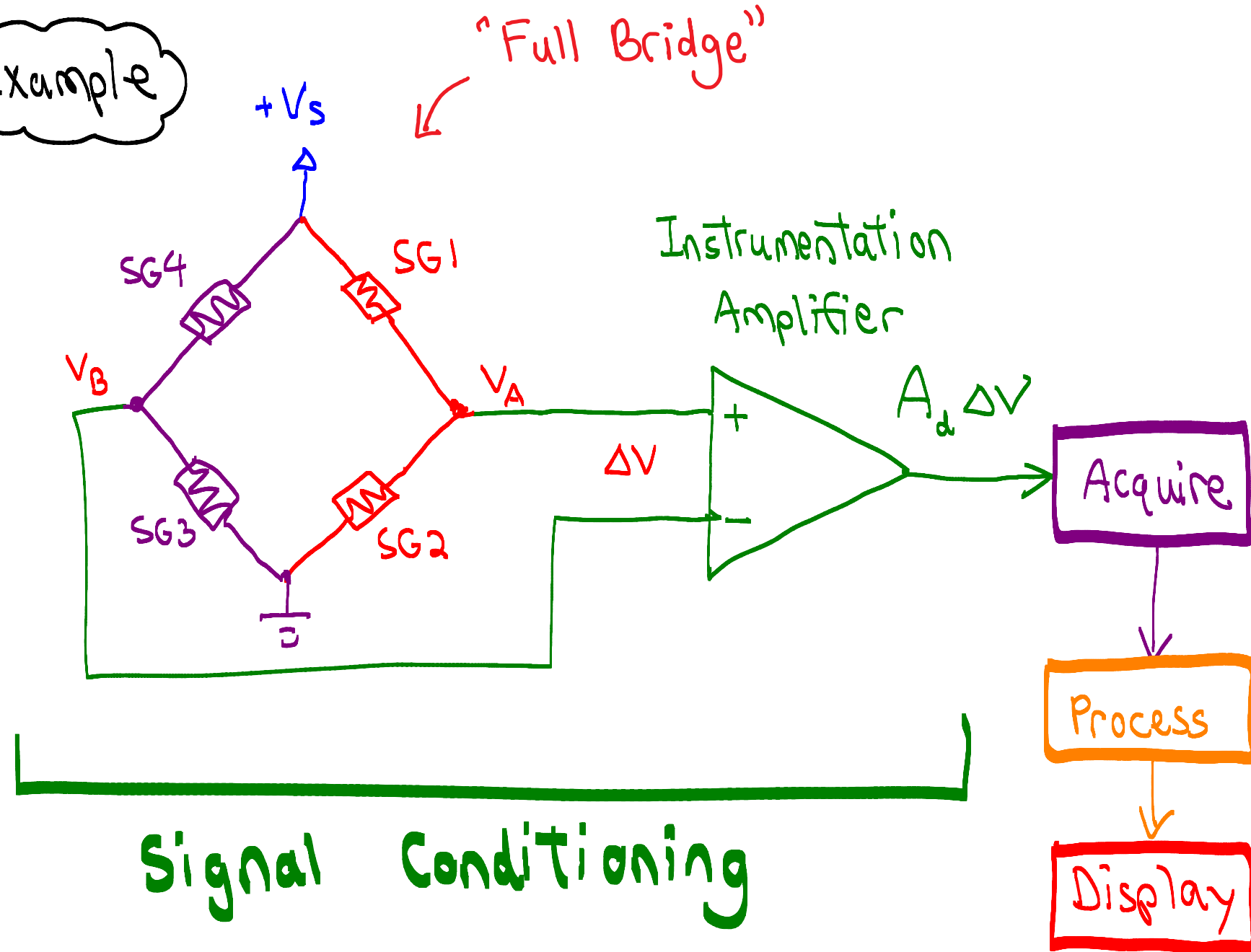
A. How to make a recording?

- To be useful, a strain gauge must be part of a circuit!

Example:



Example



B. Resistor Bridge

- Classic method to detect tiny ΔR (e.g. 0.01Ω)
 $\Rightarrow$ Bridge has 4 resistor "legs"
 $\Rightarrow$ Sensor affects $V_A - V_B$

$$\bullet V_A = V_s \frac{R + \Delta R}{(R + \Delta R) + (R - \Delta R)} = V_s \frac{R + \Delta R}{2R}$$

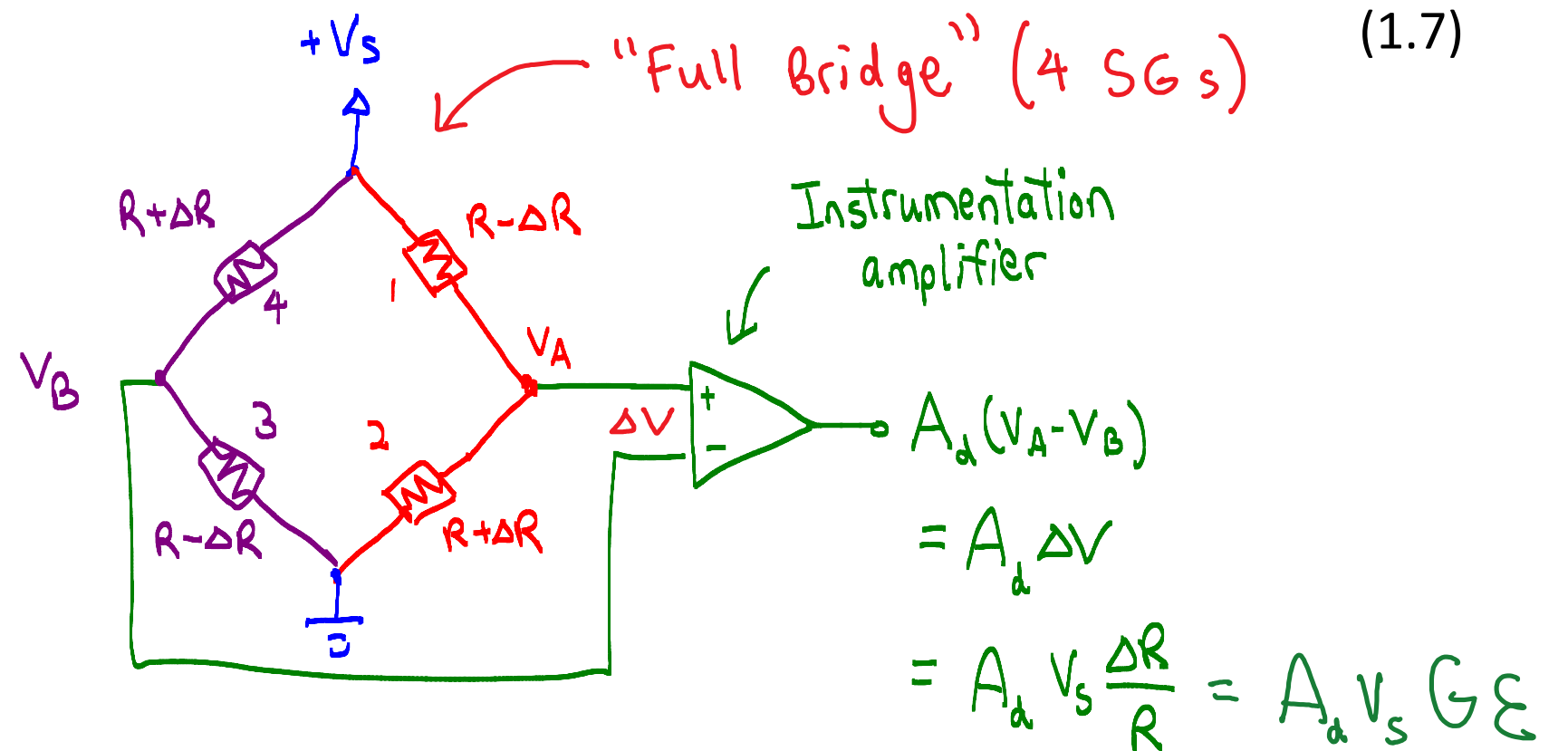
$$= \boxed{V_s \times \frac{1}{2}} + \boxed{V_s \frac{\Delta R}{2R}}$$

$$\bullet V_B = \boxed{V_s \times \frac{1}{2}} - \boxed{V_s \frac{\Delta R}{2R}} \quad \leftarrow \begin{array}{l} \text{Const} \\ \text{tiny change} \end{array}$$

$$\Rightarrow \overbrace{V_A - V_B}^{\Delta V} = 0 + V_s \frac{\Delta R}{R}$$

send this tiny voltage through an amplifier

NOTE: This assumes opposite strain between SG1 and SG2
 (SG3) (SG4)



C. Instrumentation Amplifier ← Discuss details later...

Ref [4]

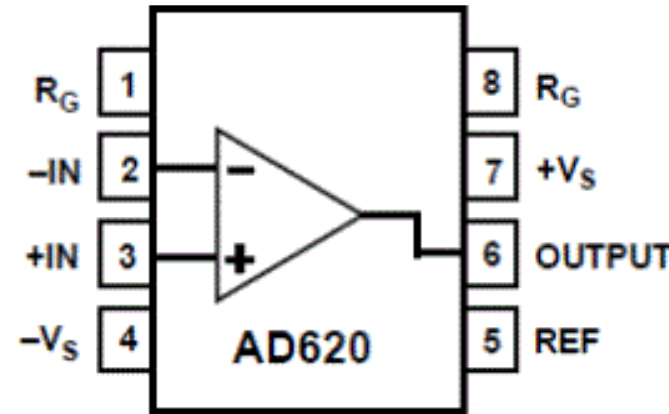
(1.8)

- Used in many biomedical measurement systems
- Amplifies the difference between two inputs



Low Cost Low Power Instrumentation Amplifier

AD620



APPLICATIONS

Weigh scales

ECG and medical instrumentation

Transducer interface

Data acquisition systems

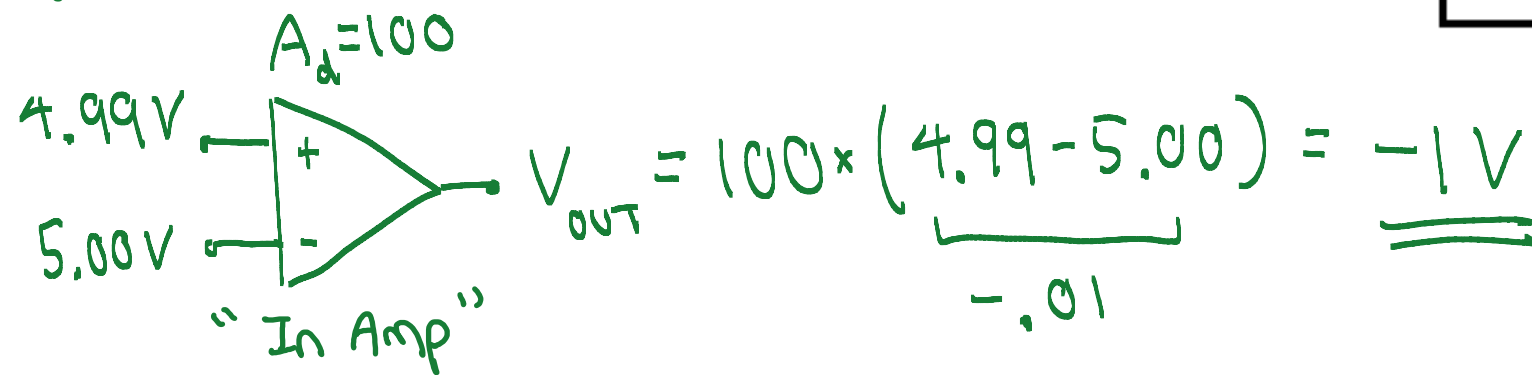
Industrial process controls

Battery-powered and portable equipment

$$V_{OUT} = A_d (V_{IN+} - V_{IN-})$$

↑
Differential Gain

Ex:



$$V_{OUT} = 100 \times (4.99 - 5.00) = \underline{\underline{-1V}}$$

-0.01

↑ NOT the same as
an op amp

Can be configured to
make a variety of circuits
(integrator, summing, etc.)

we are using
this kind, but
there are lots
of others...

D. Processing

1.9

Q: once we measure $A_d \Delta V$, how do we get strain?

Example: For full bridge:

$$V_{\text{measure}} = A_d \boxed{\Delta V} = A_d V_s \boxed{\frac{\Delta R}{R}} = A_d V_s G \epsilon$$

Measure this $\nearrow$

$\nwarrow$ we want this!

$\Rightarrow$ use algebra to solve for ϵ !

$$\epsilon = \frac{1}{A_d G V_s} \cdot V_{\text{meas}}$$

Physically meaningful quantity $\nearrow$

$\nwarrow$ data from circuit

Conversion Factor ($\frac{1}{\text{Volt}}$)

Example: $V_{\text{measure}} = .5V$

$$A_d = 500$$

$$G = 2.1$$

$$V_s = 5V$$

For full bridge:

$$\begin{aligned} \Rightarrow \epsilon &= \frac{1}{500 \times 2.1 \times 5V} \times 0.5V \\ &= \left(1.9 \times 10^{-4} \frac{1}{V} \right) \times 0.5V \\ &= 9.5 \times 10^{-5} = 95 \times 10^{-6} \\ &= \underline{\underline{95 \text{ microstrain}}} \end{aligned}$$

• Bridge Types

FULL
BRIDGE

4 active bridge legs
on the sample

$$\Delta V = V_s \frac{\Delta R}{R}$$

HALF
BRIDGE

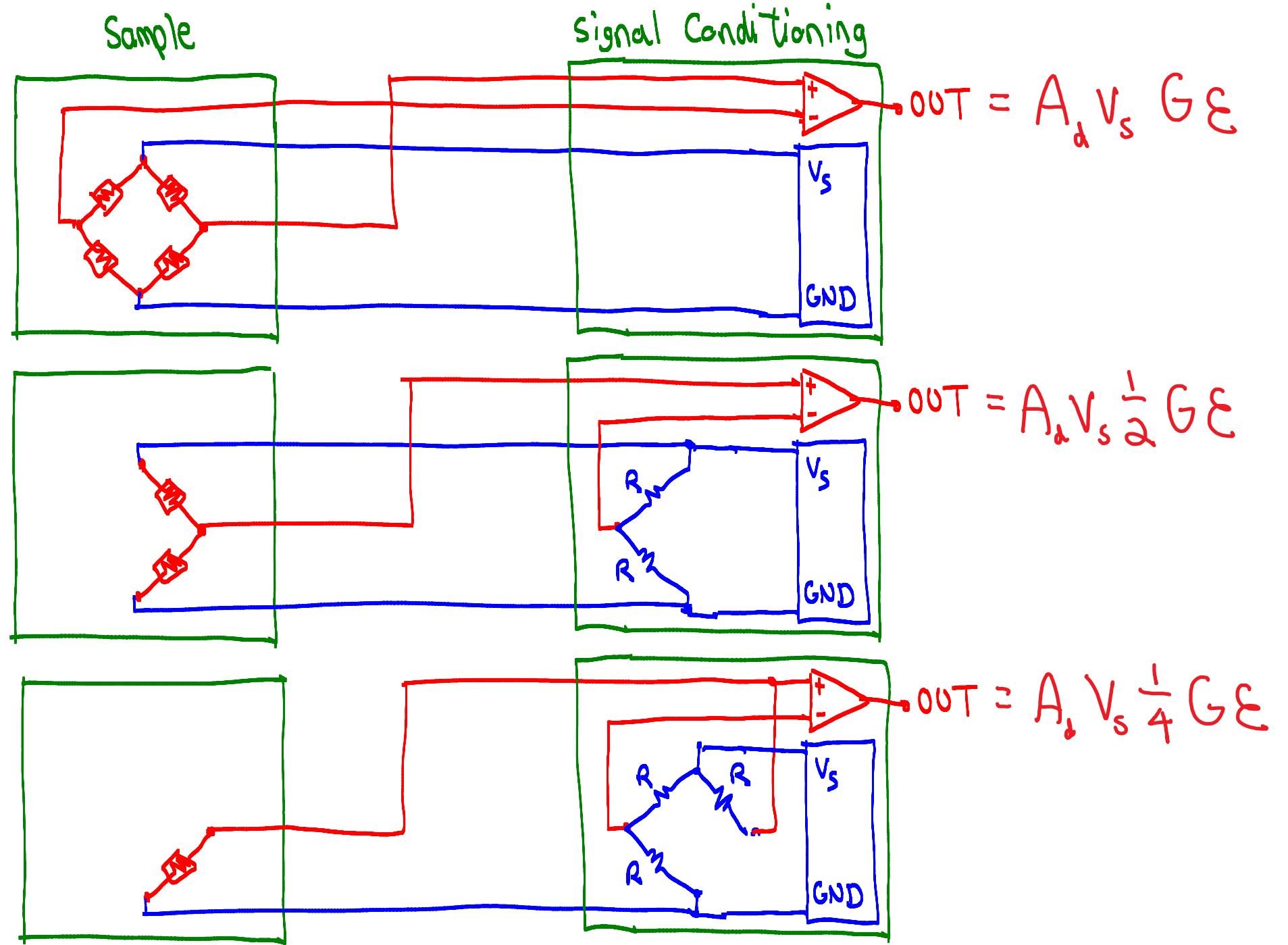
2 active bridge legs
on the sample

$$\Delta V = \frac{1}{2} V_s \frac{\Delta R}{R}$$

QUARTER
BRIDGE

1 active bridge leg
on the sample

$$\Delta V = \frac{1}{4} V_s \frac{\Delta R}{R}$$



• References

[1] Z. Yoshibash, "p-FEMs in biomechanics: Bones and Arteries",
Computer Methods in Applied Mechanics
and Engineering, v249-252, pp169-184 (2012)

[2] Instron (www.instron.us)

[3] Omega Engineering, Inc (omega.com)

[4] Analog Devices, Inc (analog.com)